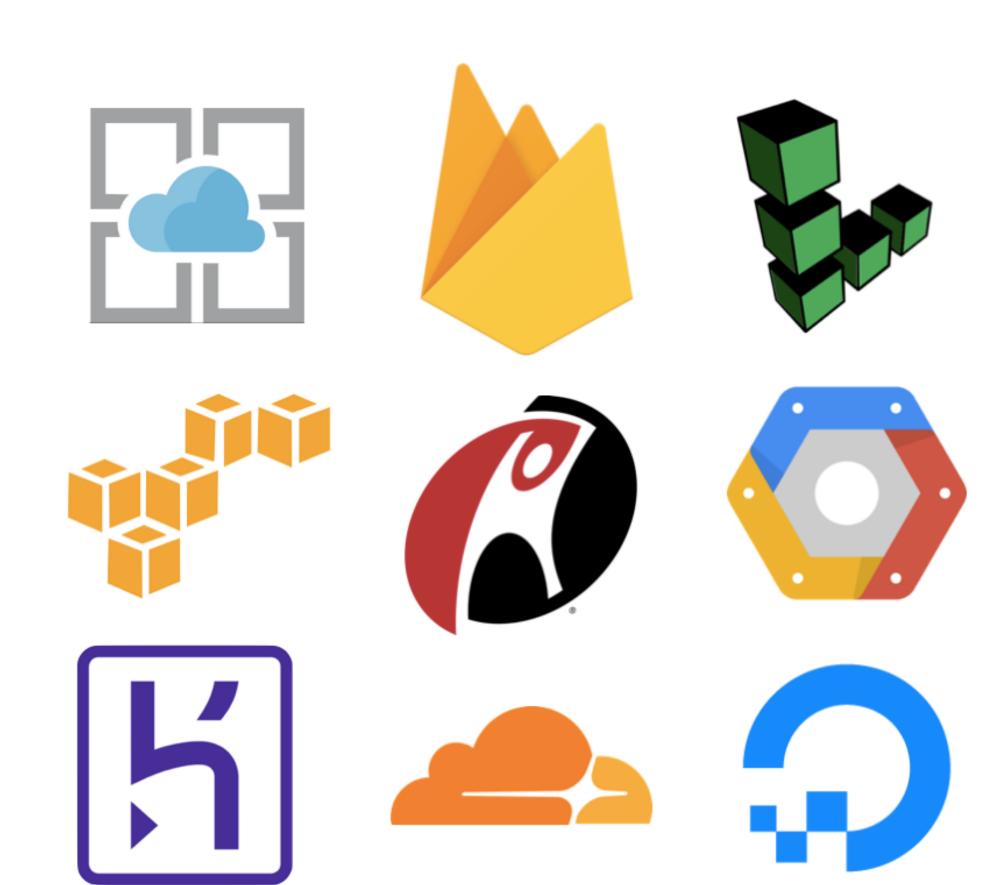
### Reasoning about Consensus Protocols

Ilya Sergey

### Consensus

- Common meaning:
   a way for a set of parties to come to a shared agreement.
- In computing: ensuring that among the values proposed by a collection of processes, a single one is chosen.
  - Uniformity: Only a single value is chosen
  - Non-triviality: Only a value that has been proposed may be chosen
  - Irrevocability: Once agreed on a value, the processes do not change their decision.

# Why Consensus?













## Why Consensus at SIGPL School?

- Because distributed systems are correctness-critical software.
- PL area provides verification methods and language abstractions.
- Reasoning about correctness of distributed consensus and its applications is a *difficult problem*.

### Why Distributed Consensus is difficult?

- Arbitrary message delays (asynchronous network)
- Independent parties (nodes) can go offline (and also back online)
- Network partitions
- Message reorderings
- Malicious (Byzantine) parties

### Why Distributed Consensus is difficult?

- Arbitrary message delays (asynchronous network)
- Independent parties (nodes) can go offline (and also back online)
- Network partitions
- Message reorderings
- Malicious (Byzantine) parties

# Reaching a Consensus

(and constructing a protocol for this)



# Reaching a Consensus on where to have a dinner

Jyoti

La Yeon

Parkview

Jyoti

La Yeon

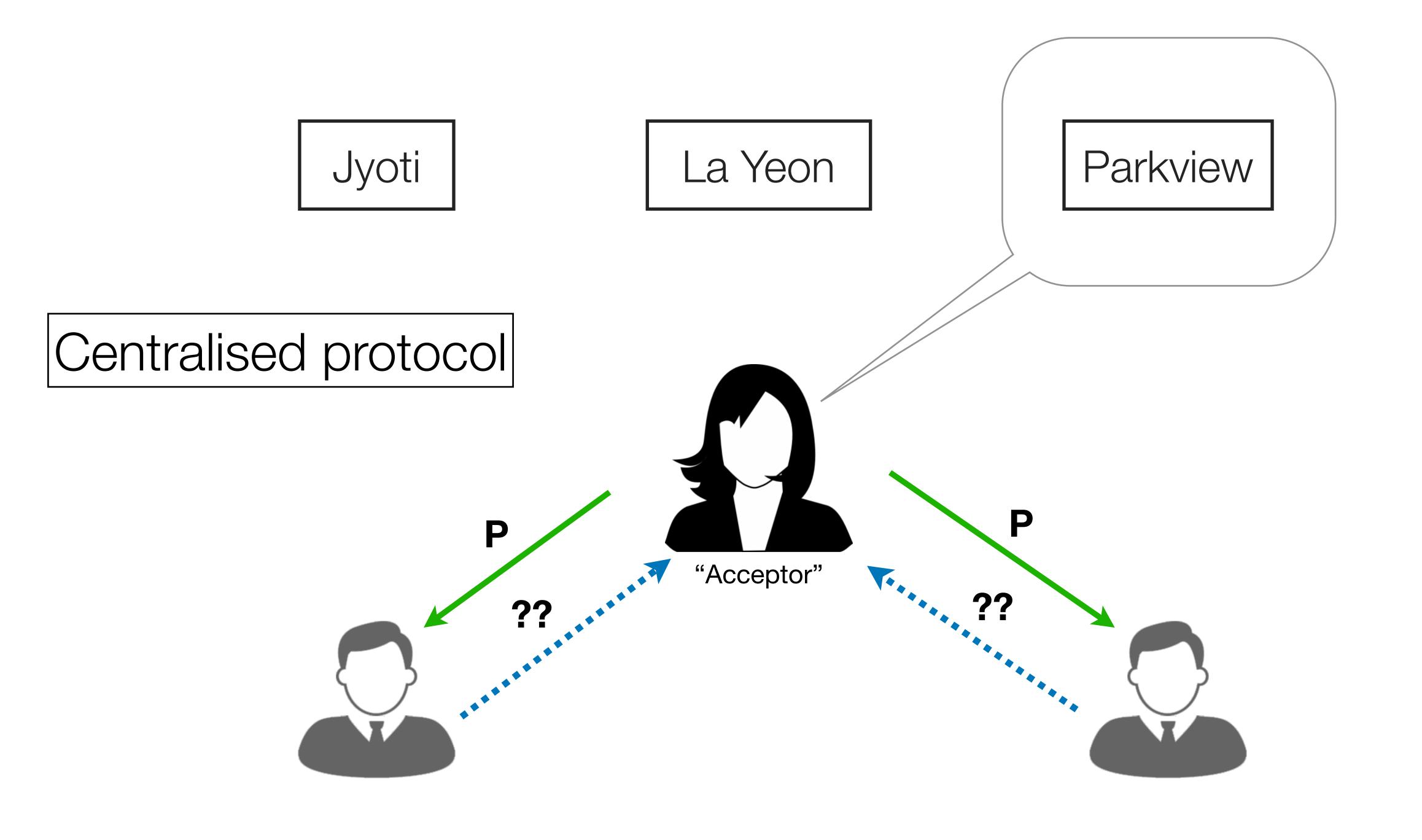
Parkview











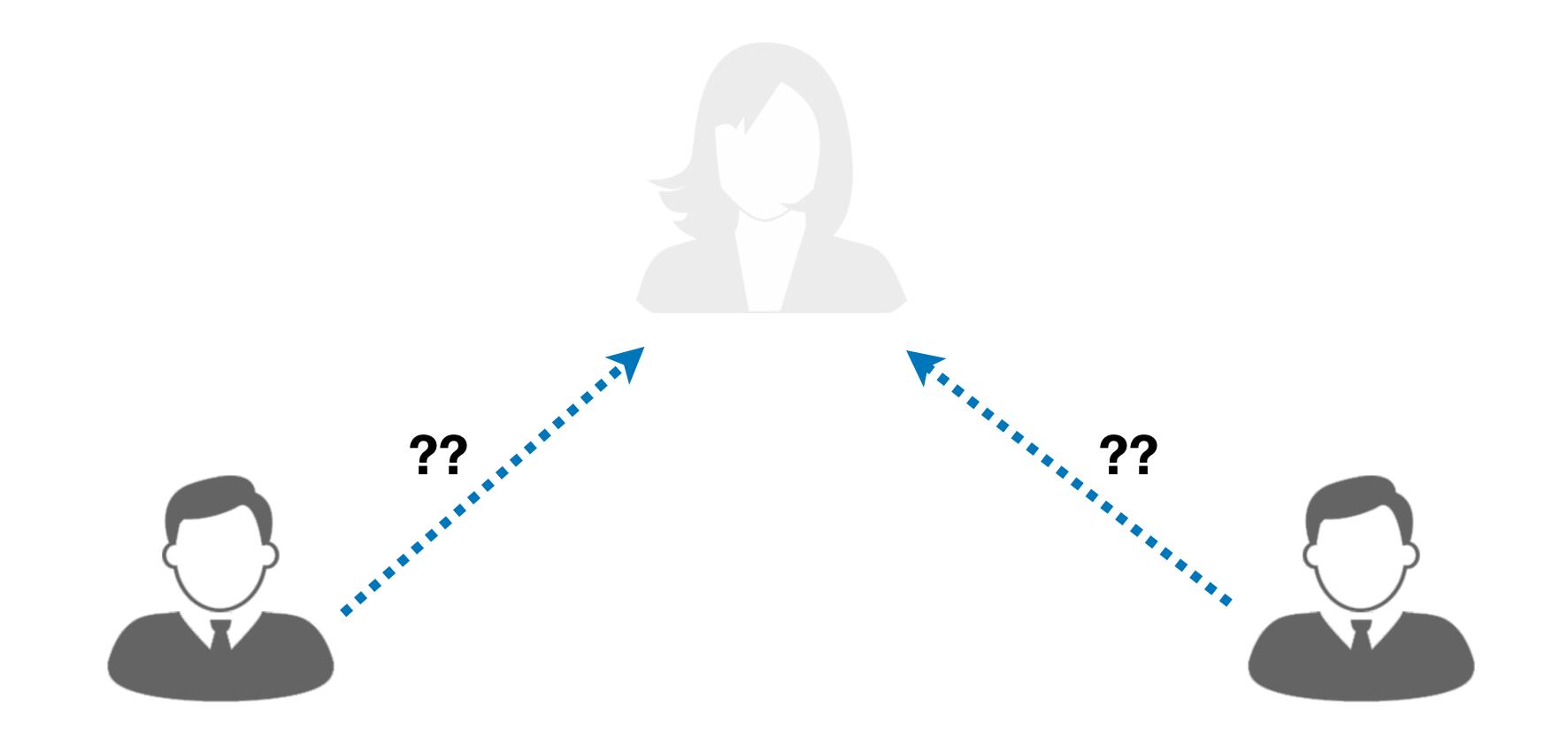
### Problem 1

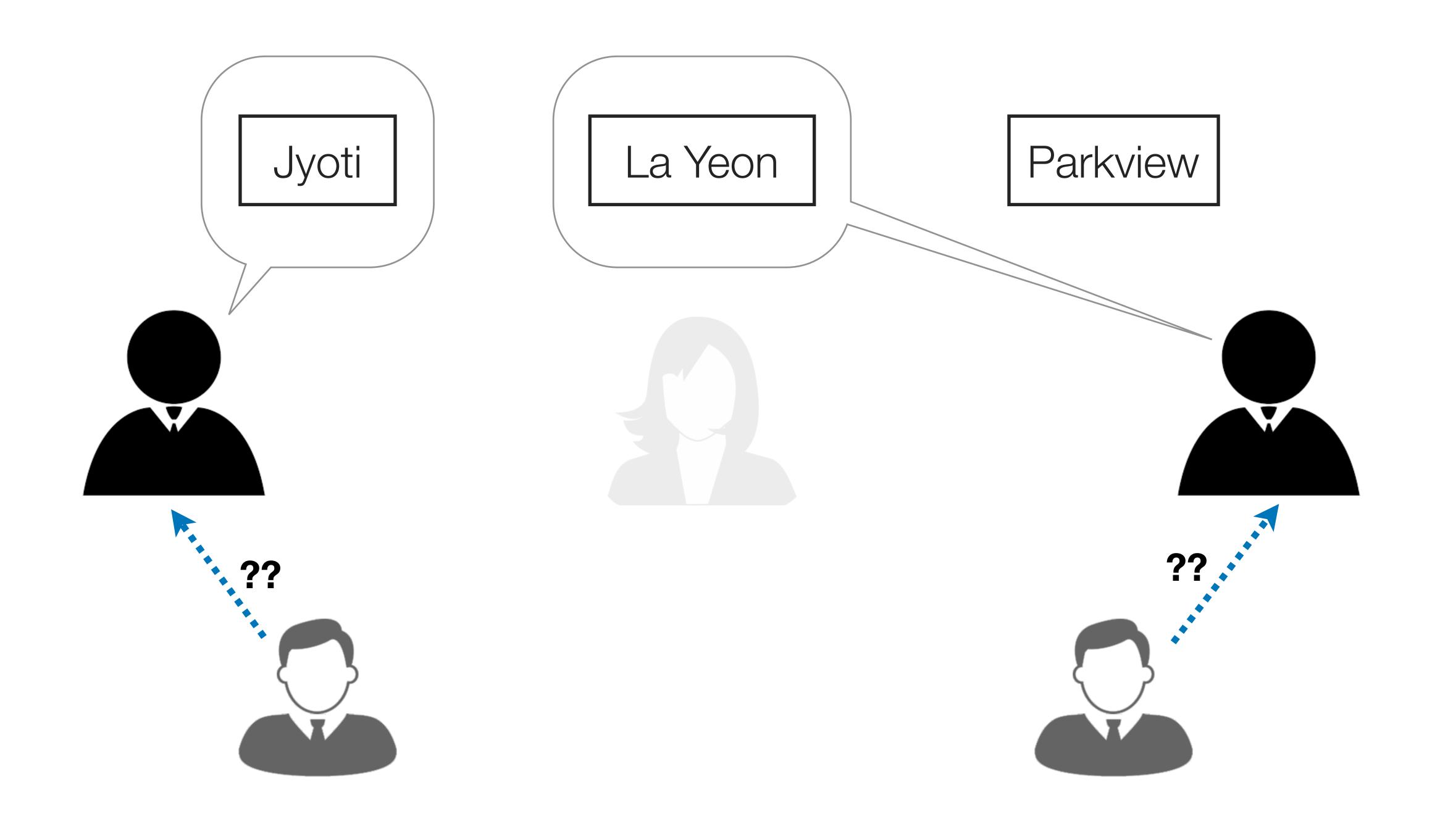
A single acceptor can go offline or take forever to answer.

Jyoti

La Yeon

Parkview





### Problem 2

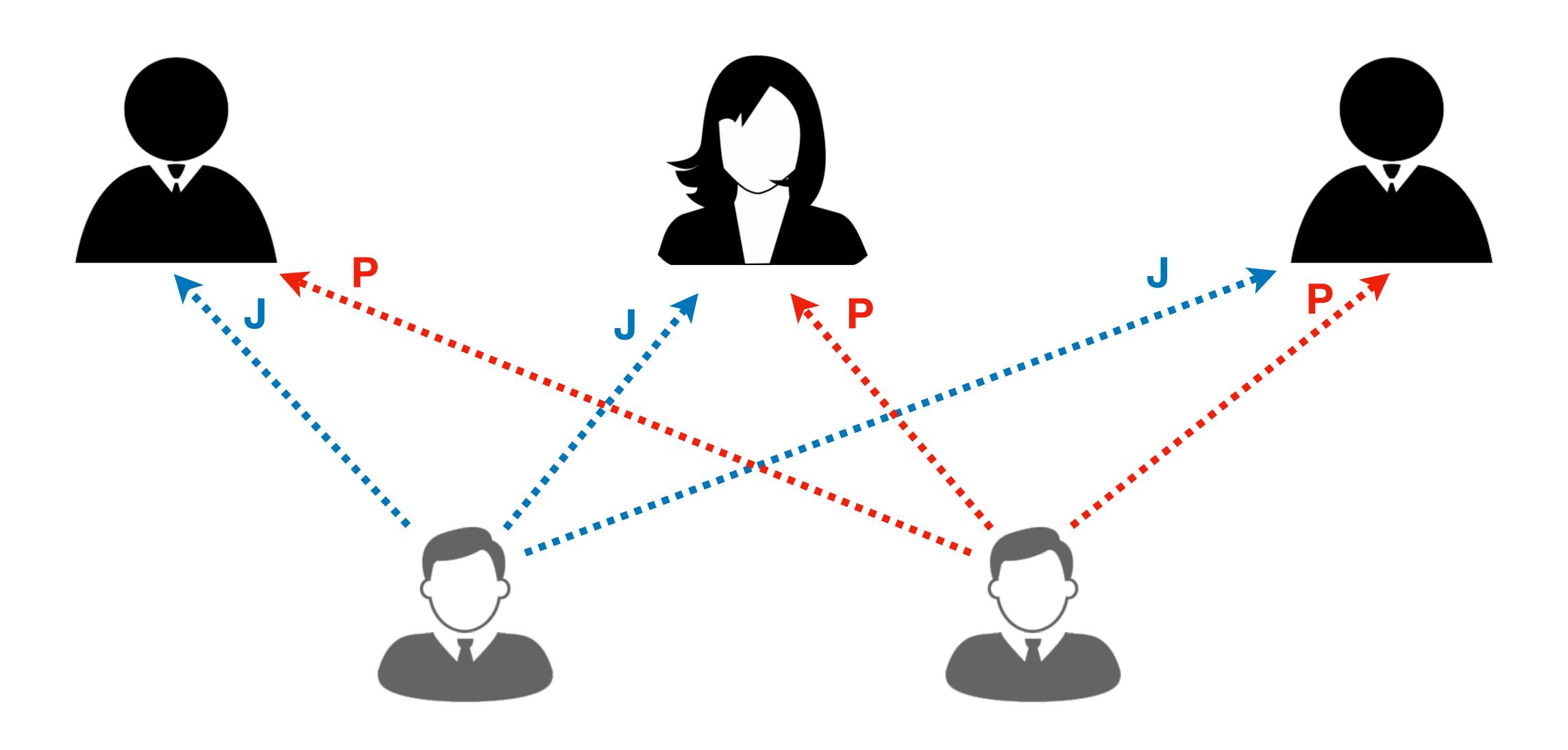
Multiple *acceptors* might disagree on the outcomes: now they need to *reach a consensus* themselves.

# Separation of Concerns

- Proposers: suggest a value (a restaurant to go);
- Acceptors: support some proposal;
- The proposer with a *majority of acceptors* supporting its proposal wins.

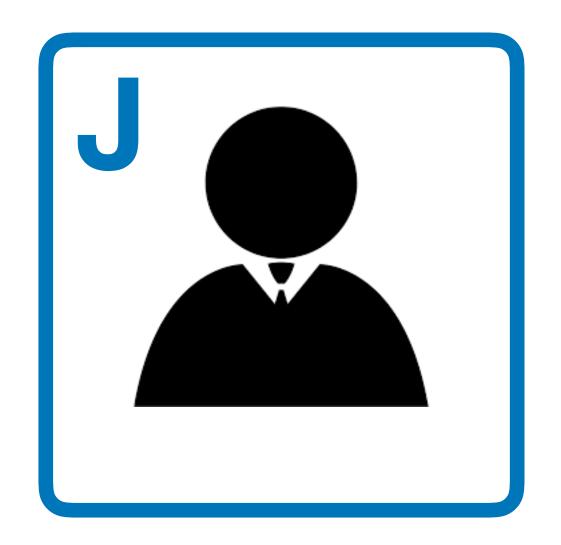
Others learn the outcome by querying all the acceptors.

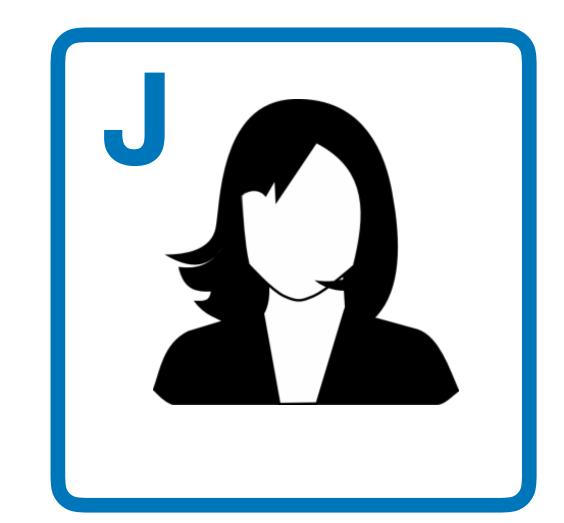
#### Acceptors

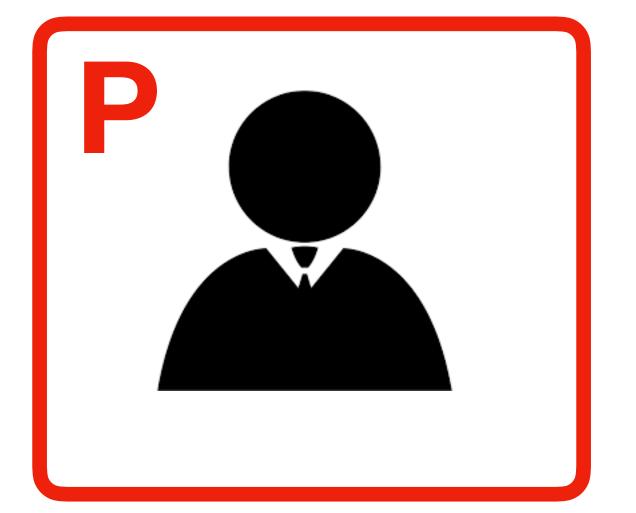


Proposers

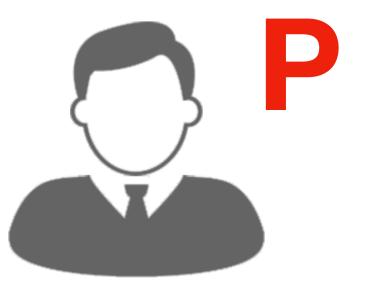
#### Acceptors











Proposers

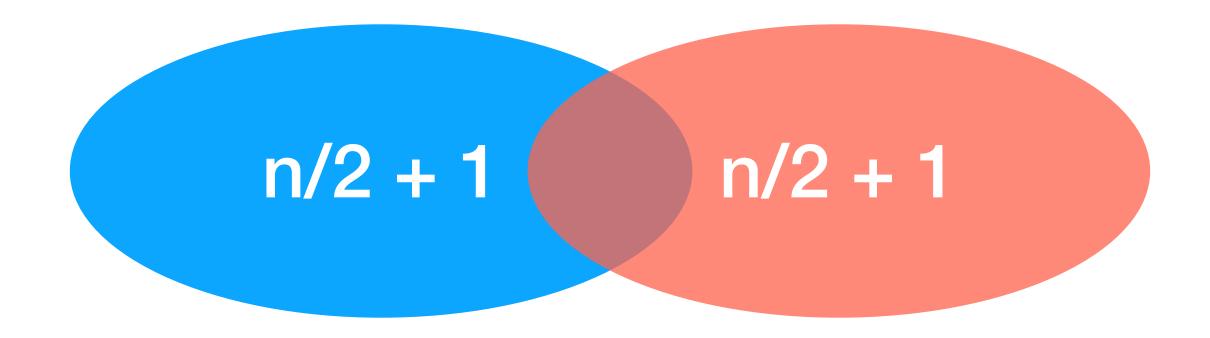
# Key Idea 1

Rely on majority quorums for agreement to prevent the "split brain" problem.

- Common meaning: Quorum is the minimum number of members to conduct the business on behalf of the entire group they represent;
- In computing: quorum is a necessary number of processes to agree on the decision in the presence of potentially faulty ones.

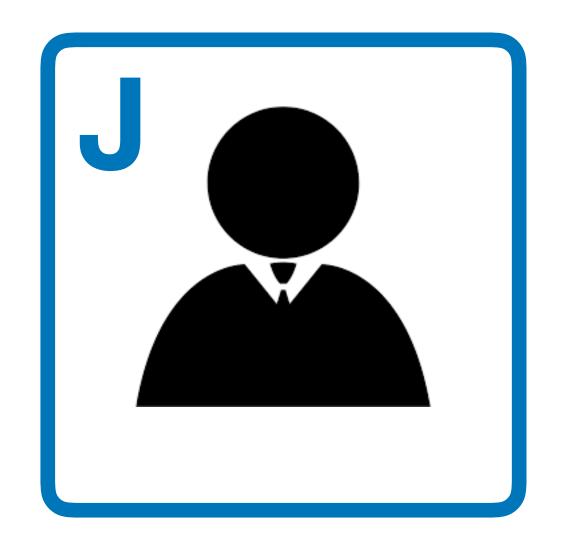
# Key Properties of Quorums

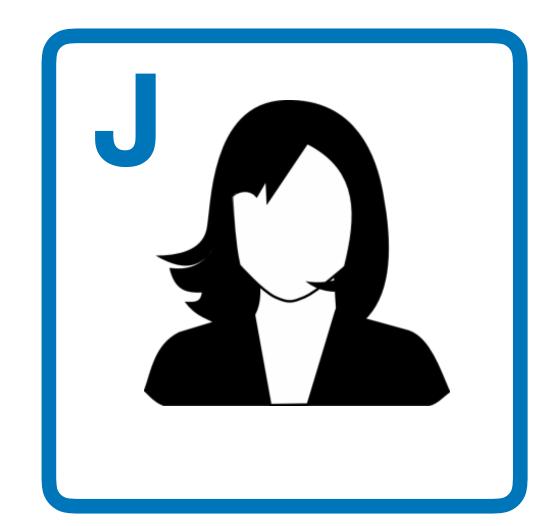
• Property 1: any two quorums must have non-empty intersection

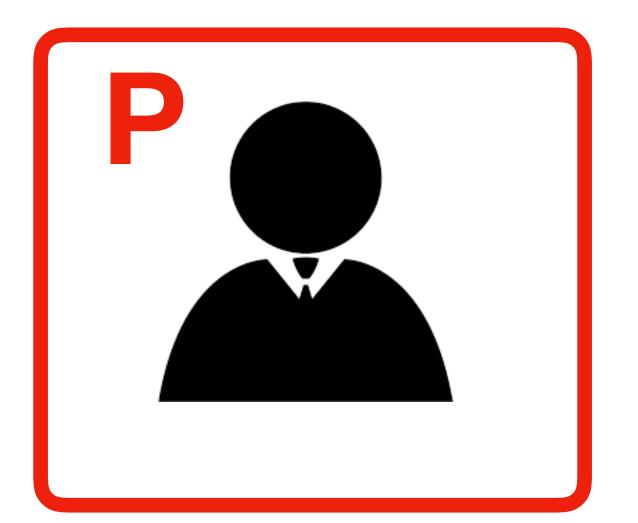


• Property 2: no need for the global agreement: can tolerate some faults

n = 3







Quorum of n/2 + 1 acceptors



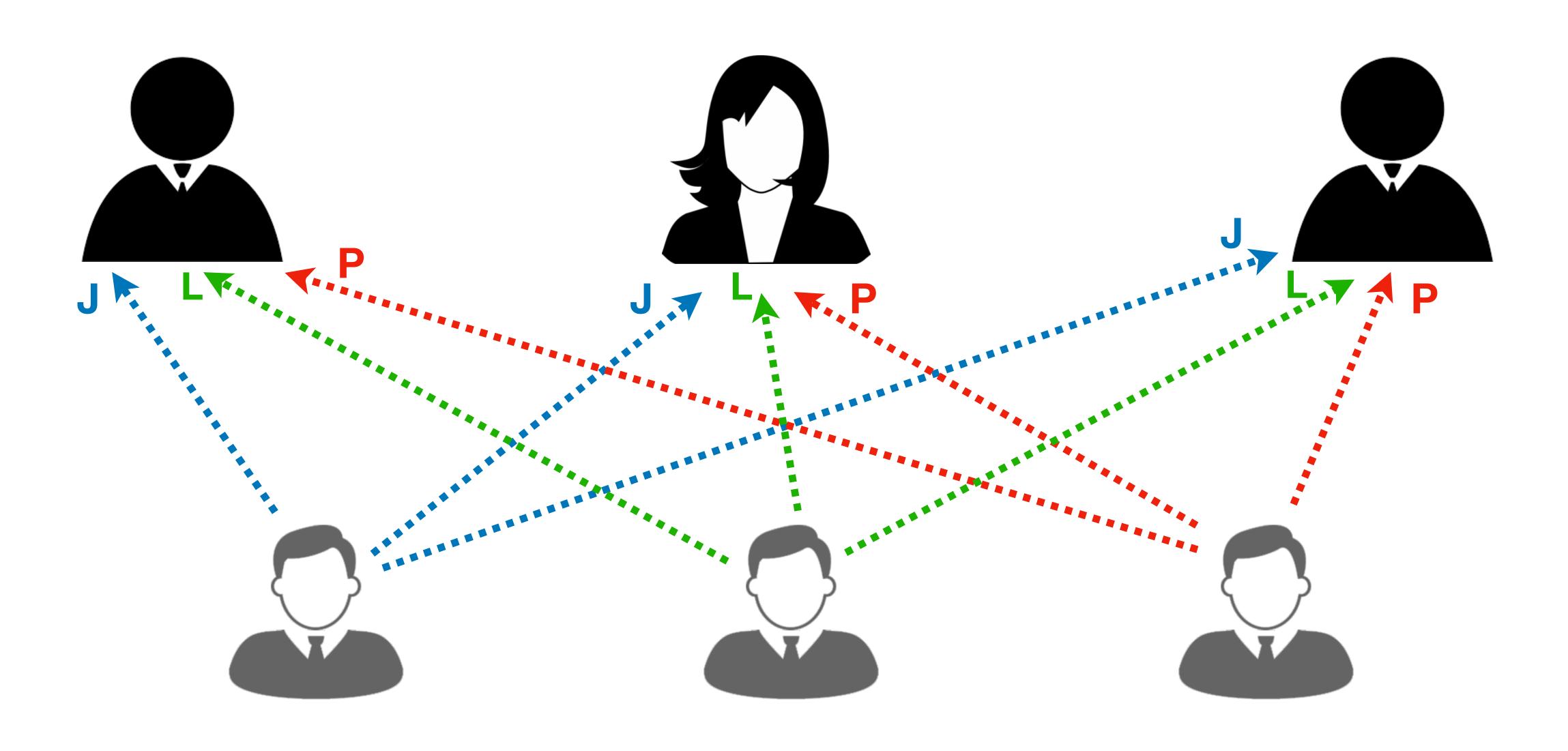


### Problem

A quorum is difficult to obtain in a single interaction.

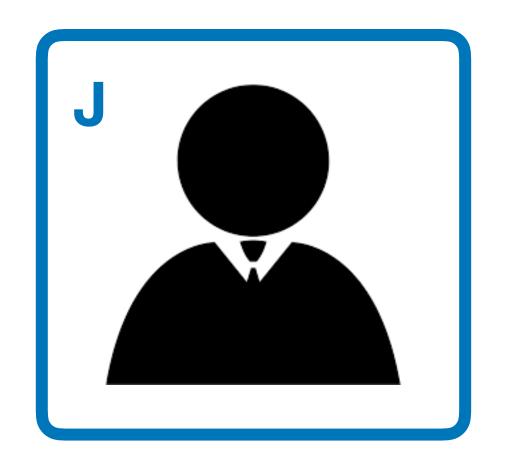
As the result, such a system will often get stuck.

#### Acceptors



Proposers

#### Acceptors













Proposers

# Key Ideas 2 and 3

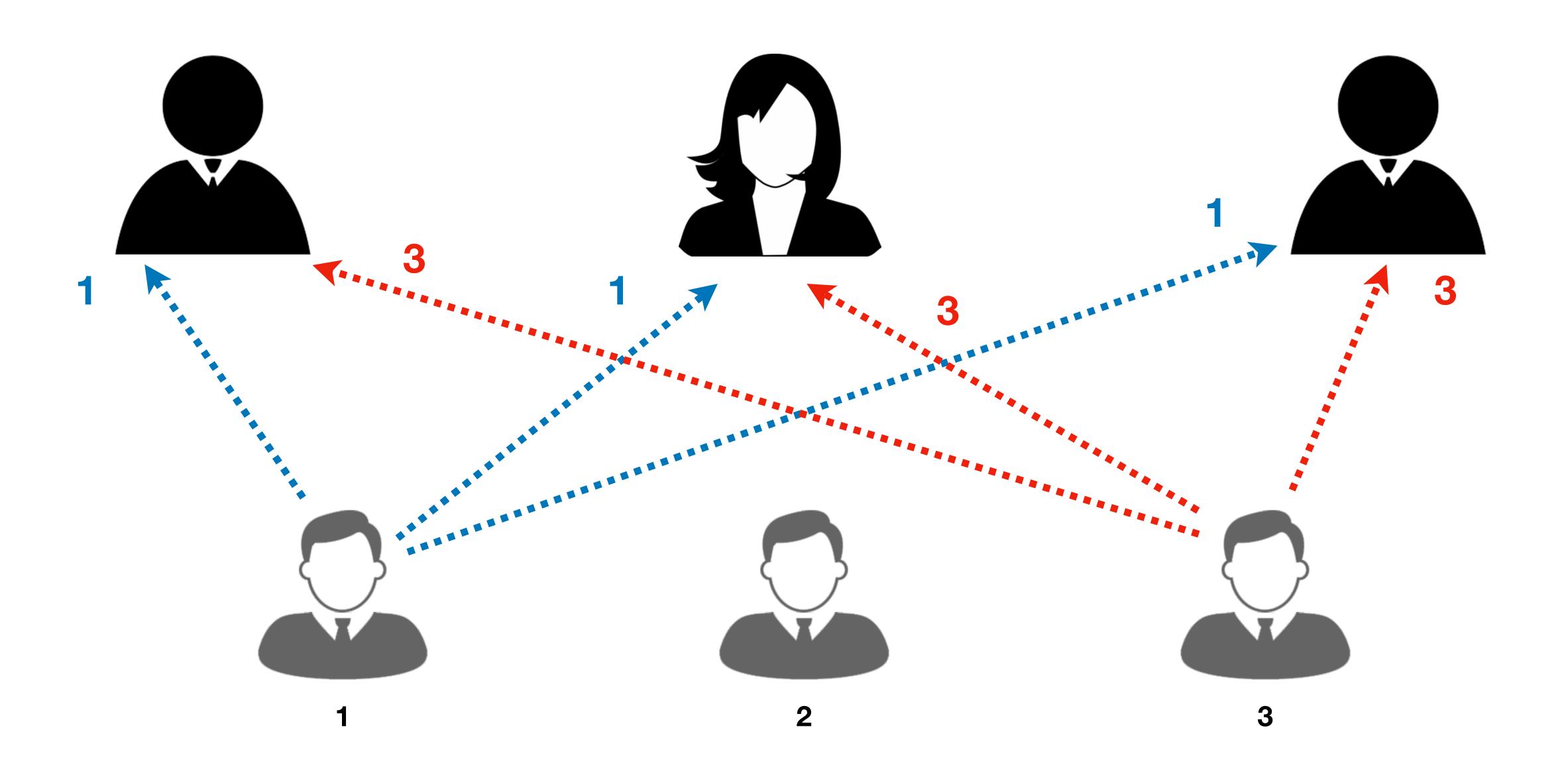
#### Proceed in rounds:

- A proposer first "secures" itself a quorum, willing to support its proposal (i.e., becomes a "leader");
- Only if a quorum is secured, it goes on to "propose" a value.
- Introduce fixed globally known *priorities* between proposers to "break ties" when securing quorums.
  - Acceptors only "choose to support" proposers with higher priorities than they have already seen.

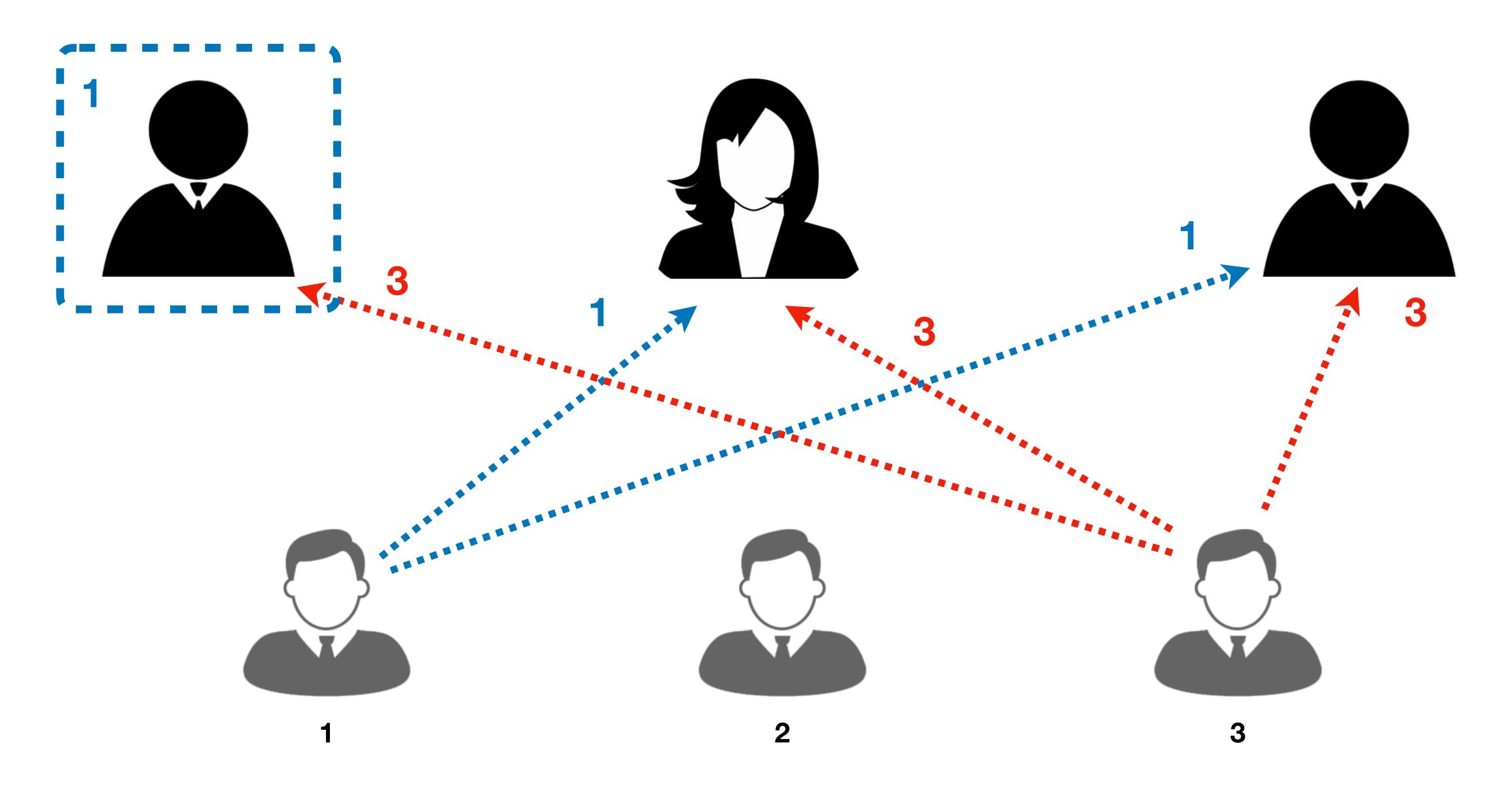
# Some Terminology

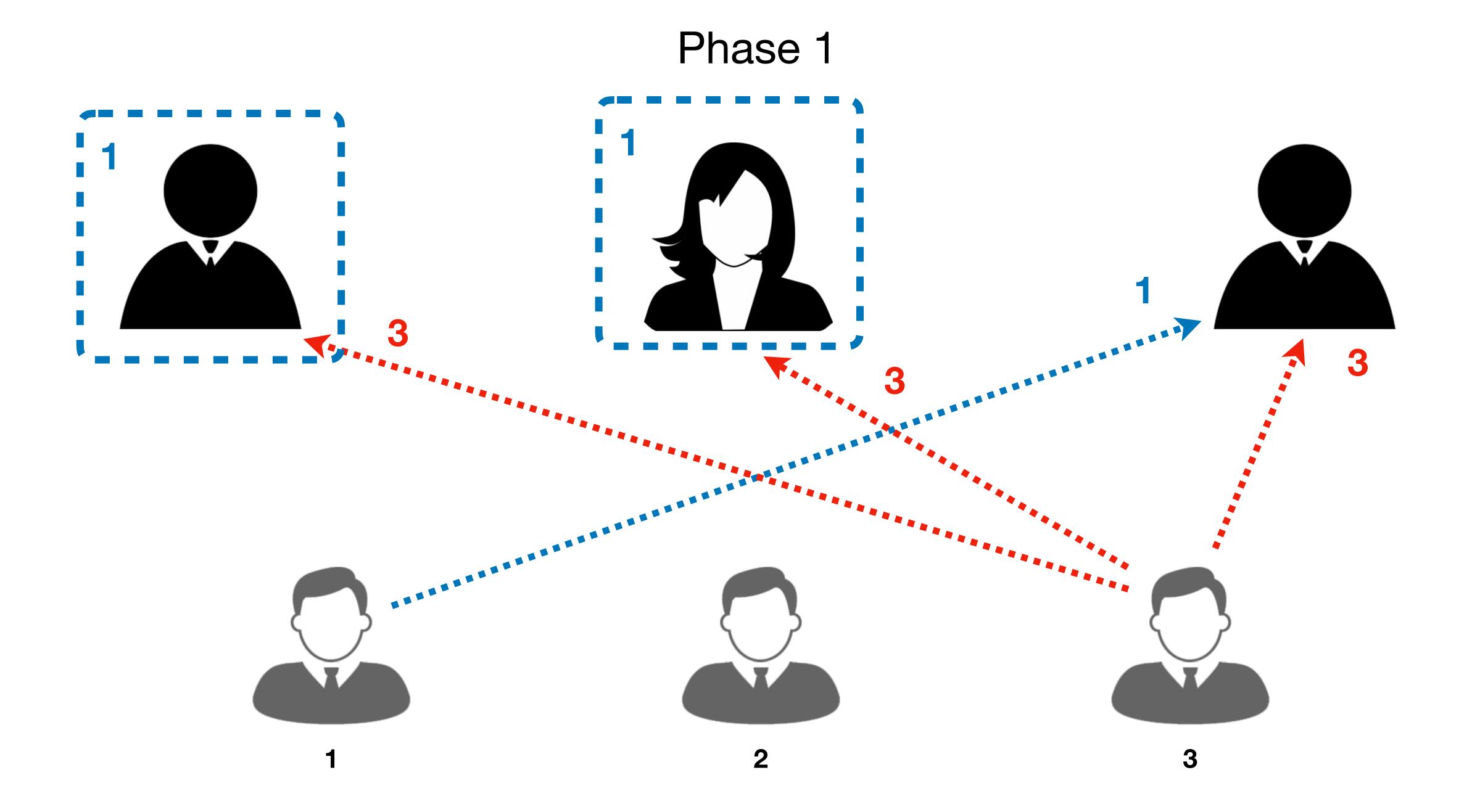
- Rounds Phases
  - Phase 1 "prepare", securing quorums to propose
  - Phase 2 "accept", sending values to accept
- Fixed priorities Ballots

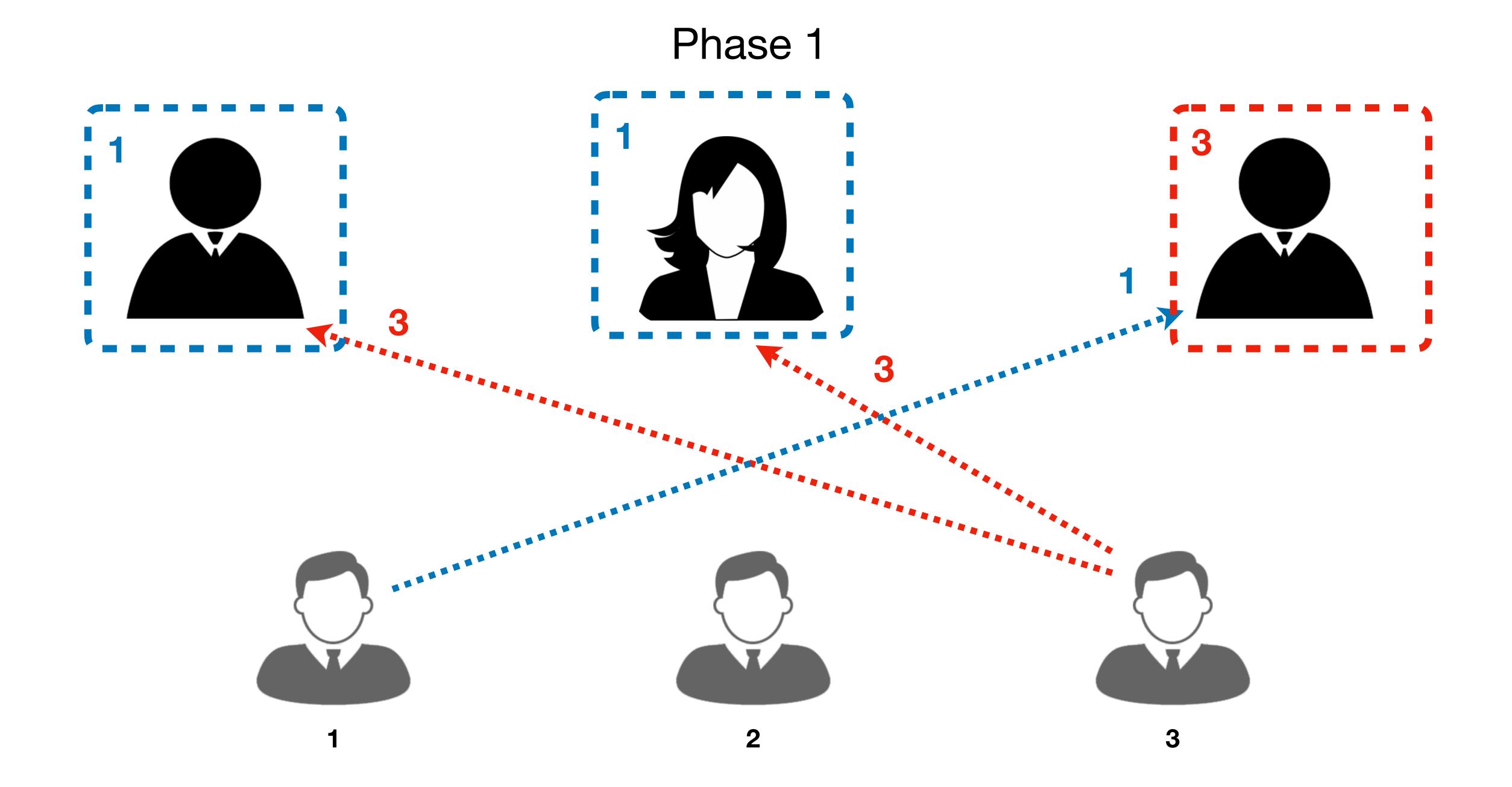
Phase 1

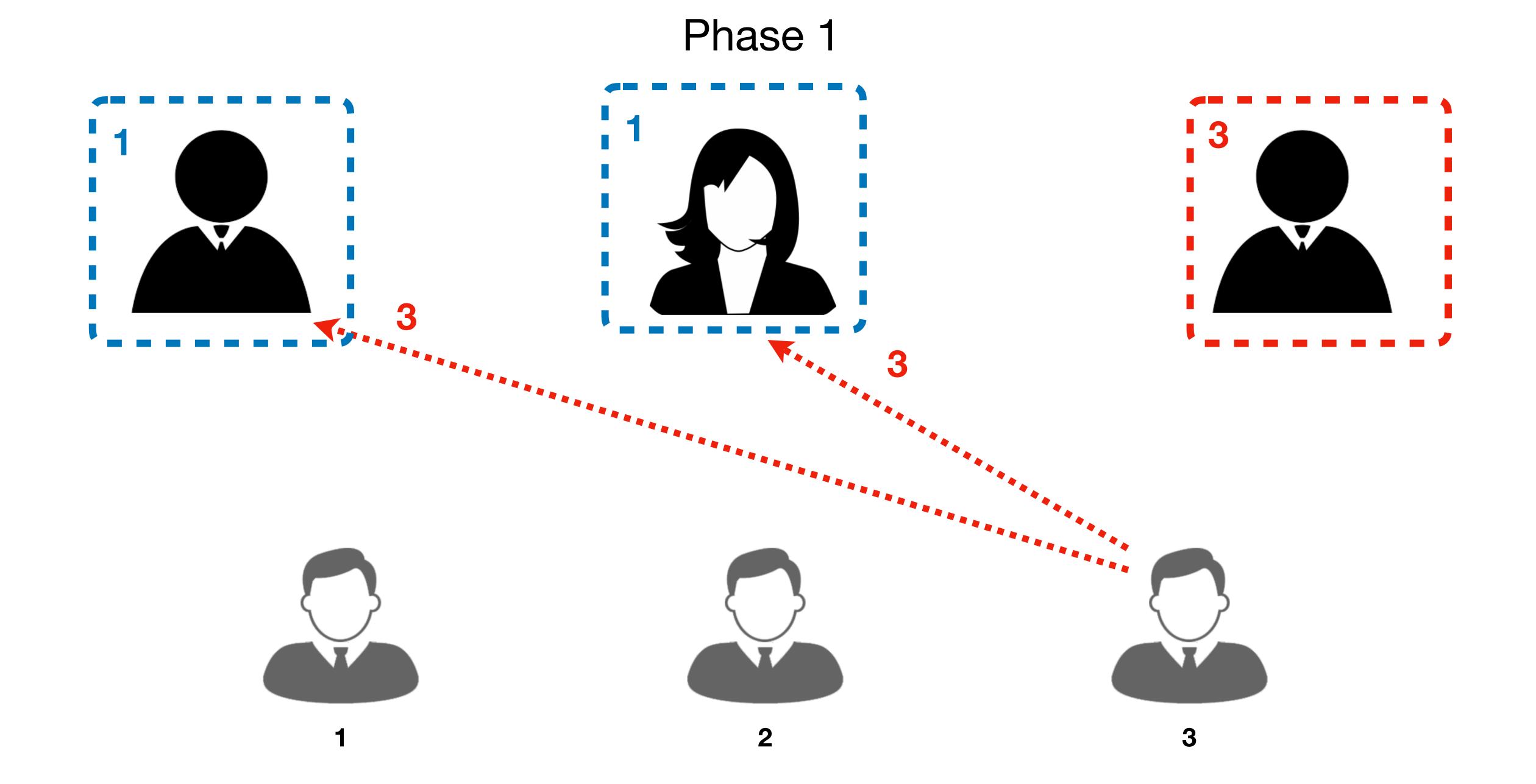


Phase 1





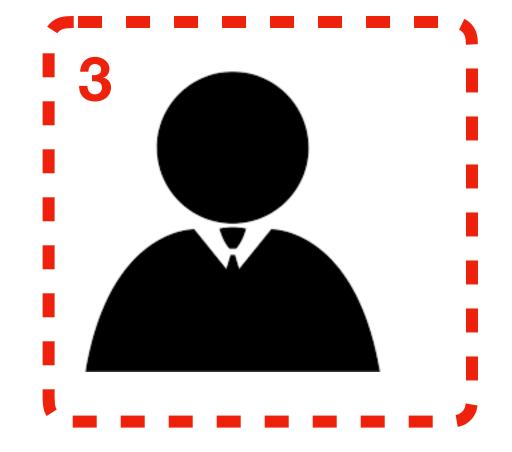




Phase 1







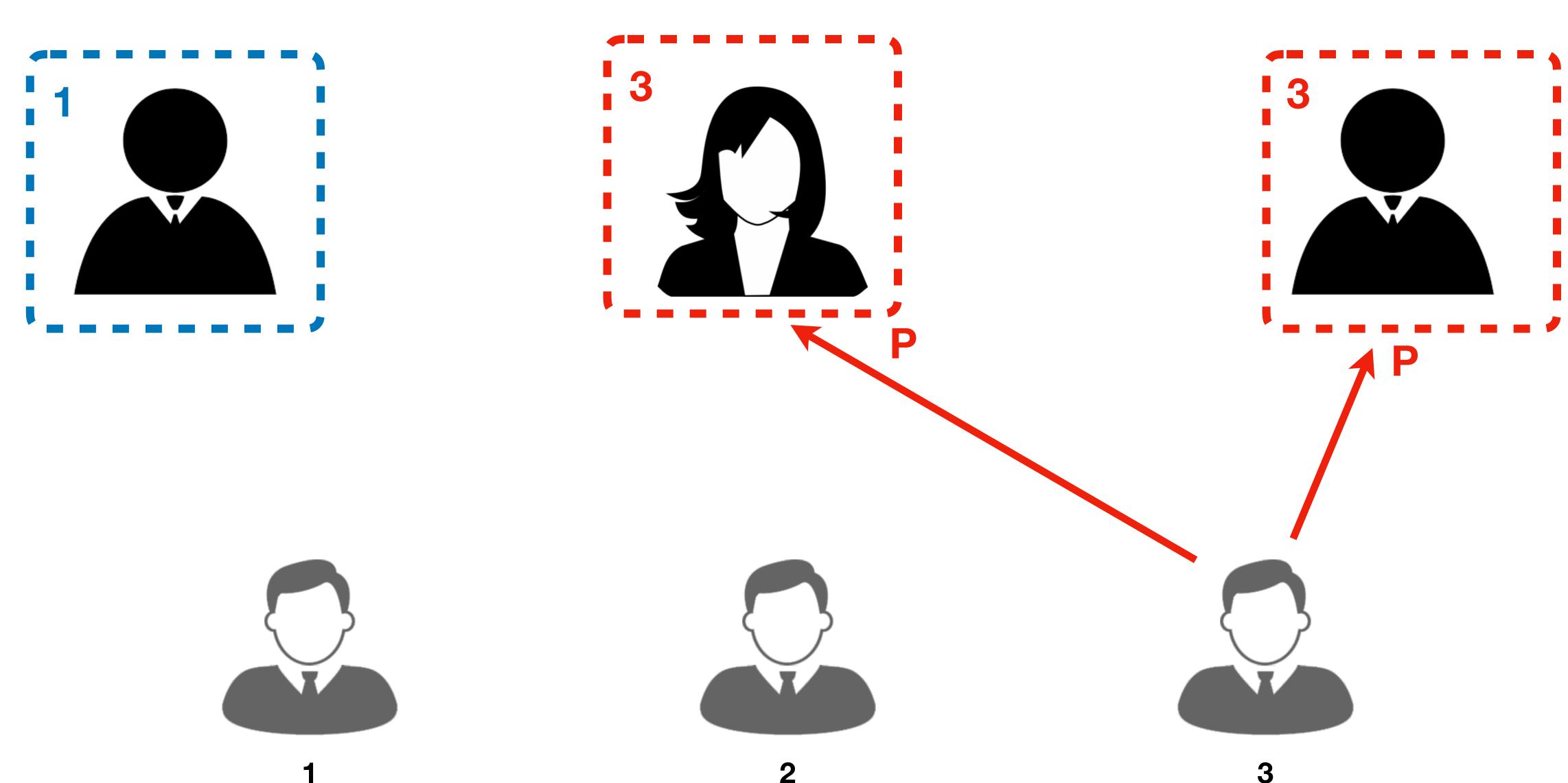






3

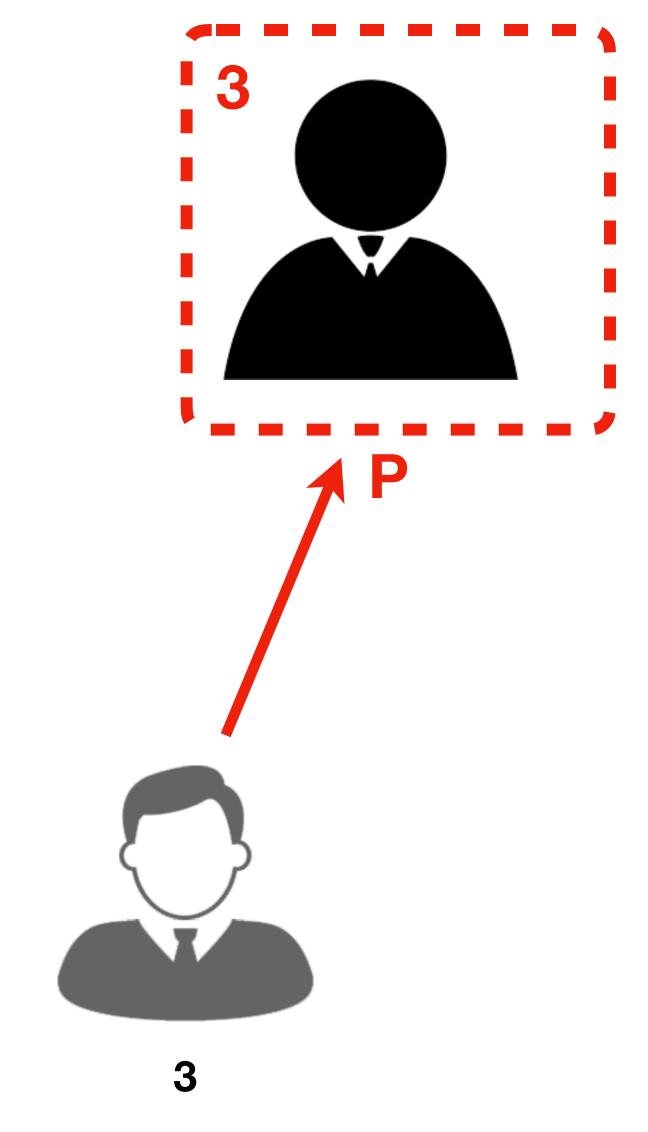
#### Phase 2



Phase 2







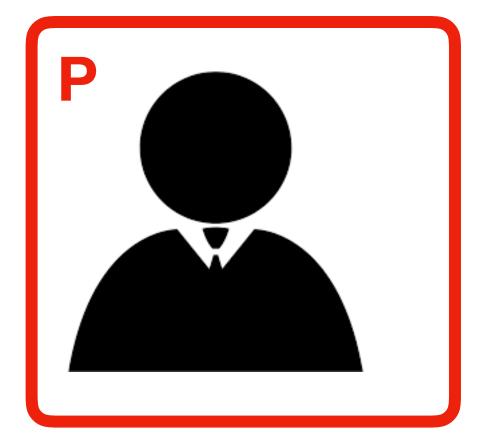




Phase 2









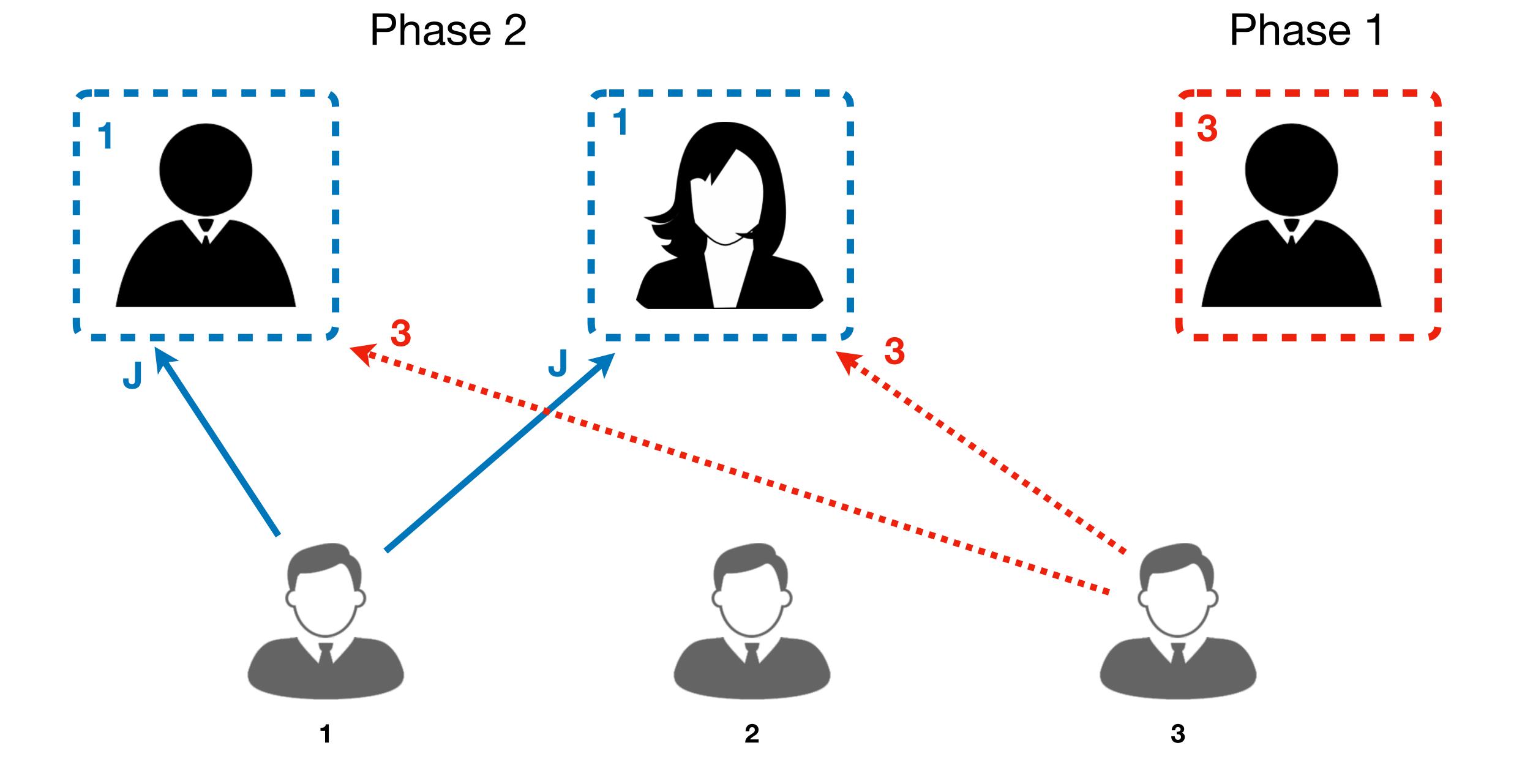


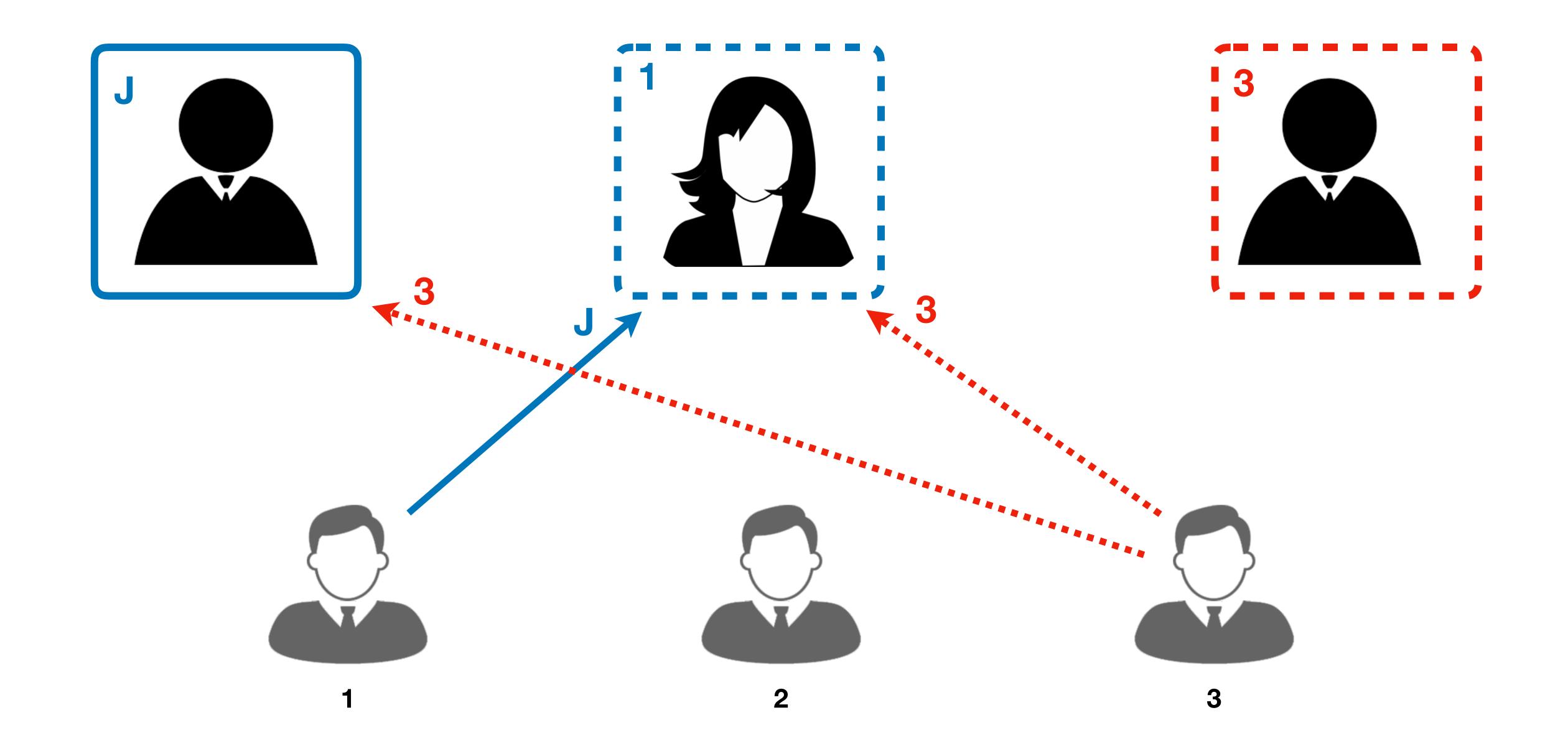


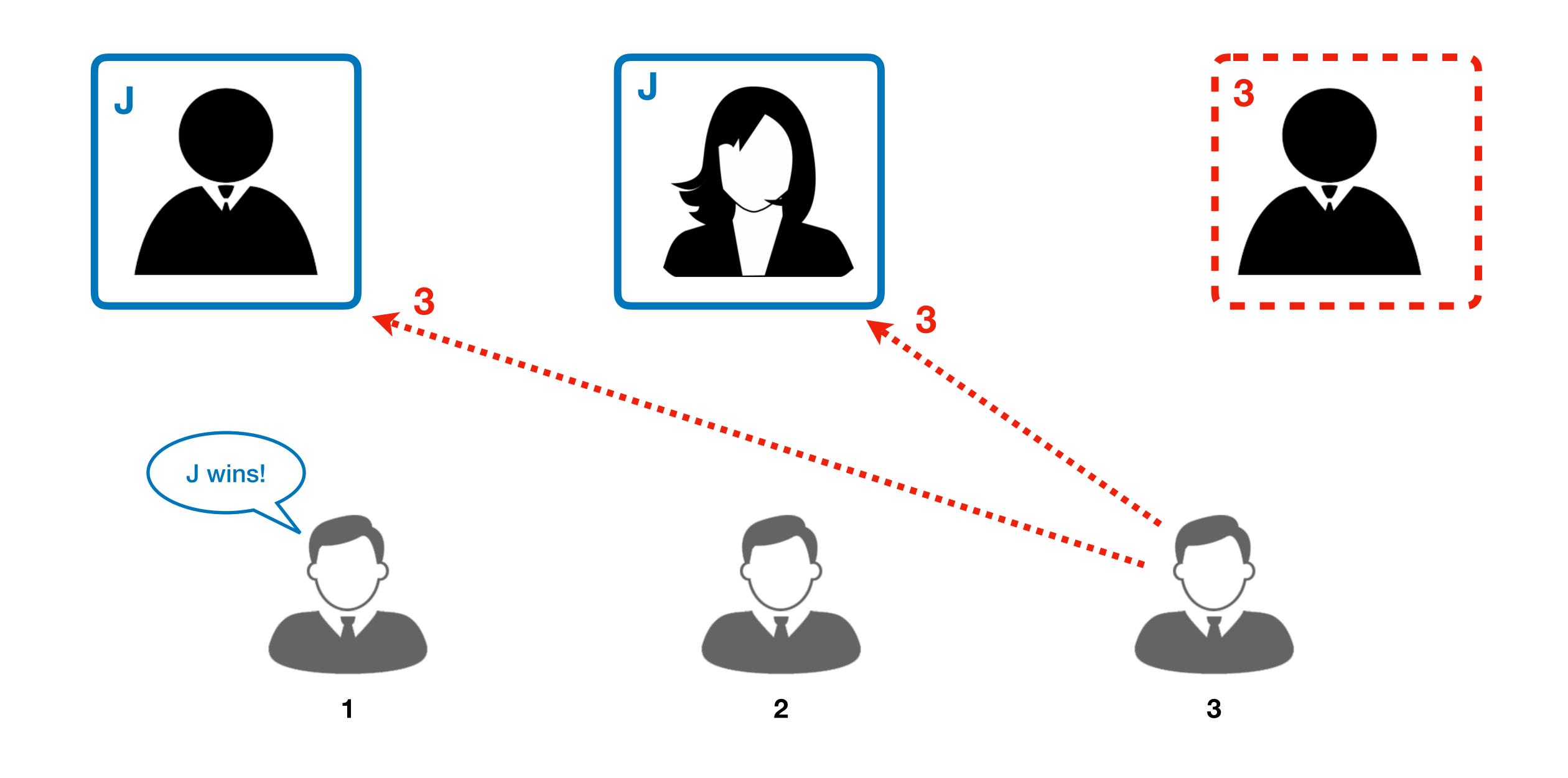
2

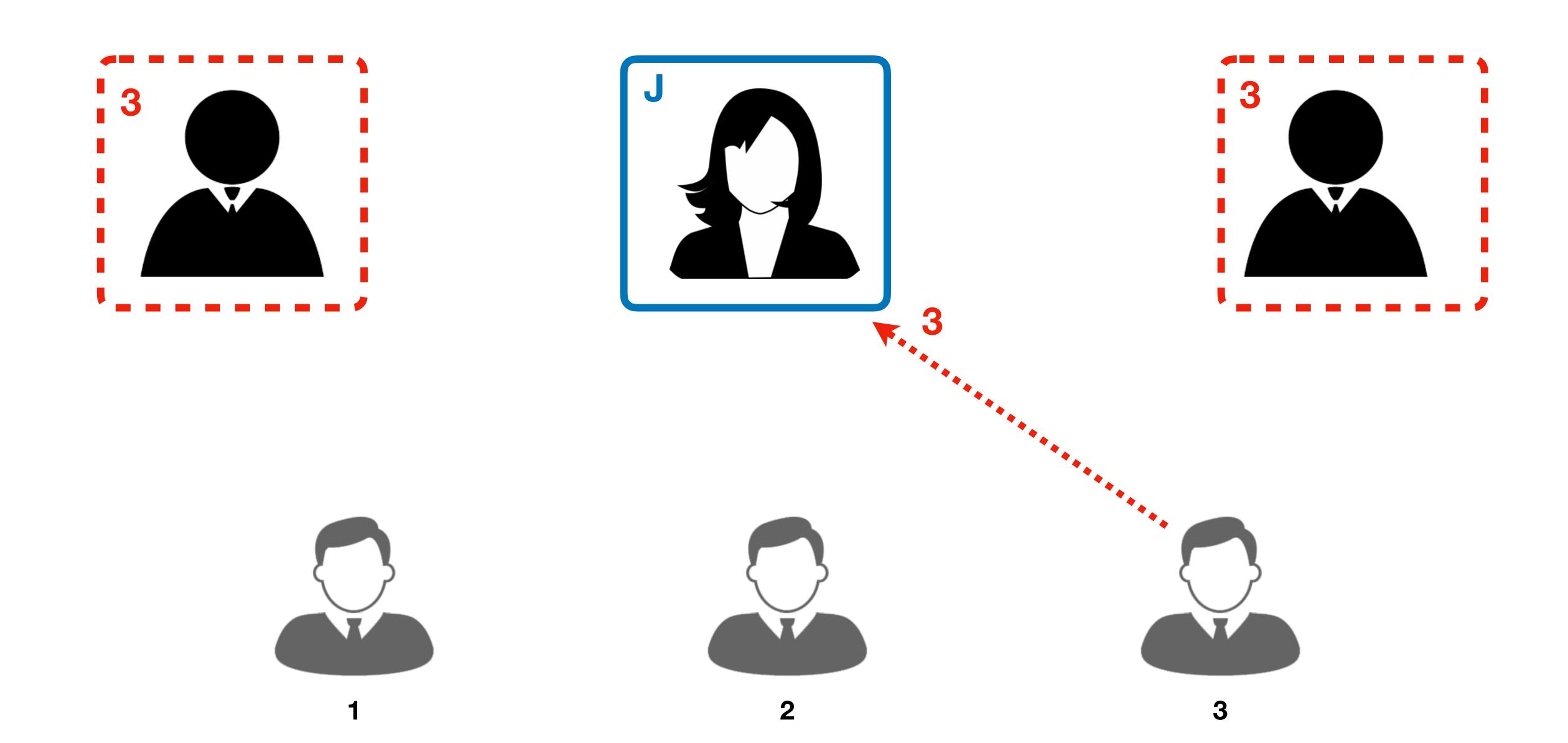
### Problem 3

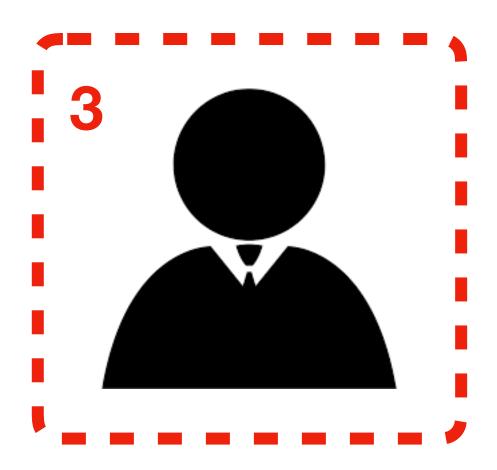
Because of asynchrony, low-priority Phase 2 can be interrupted by a high-priority Phase 1



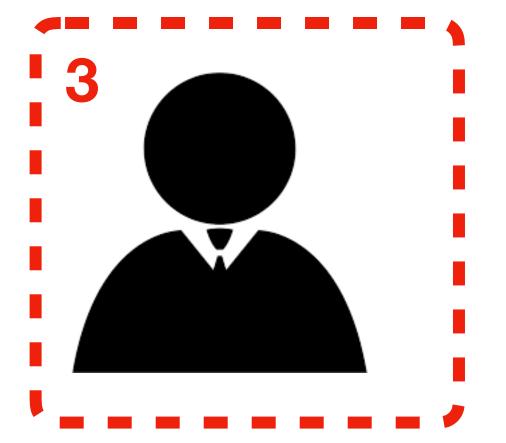








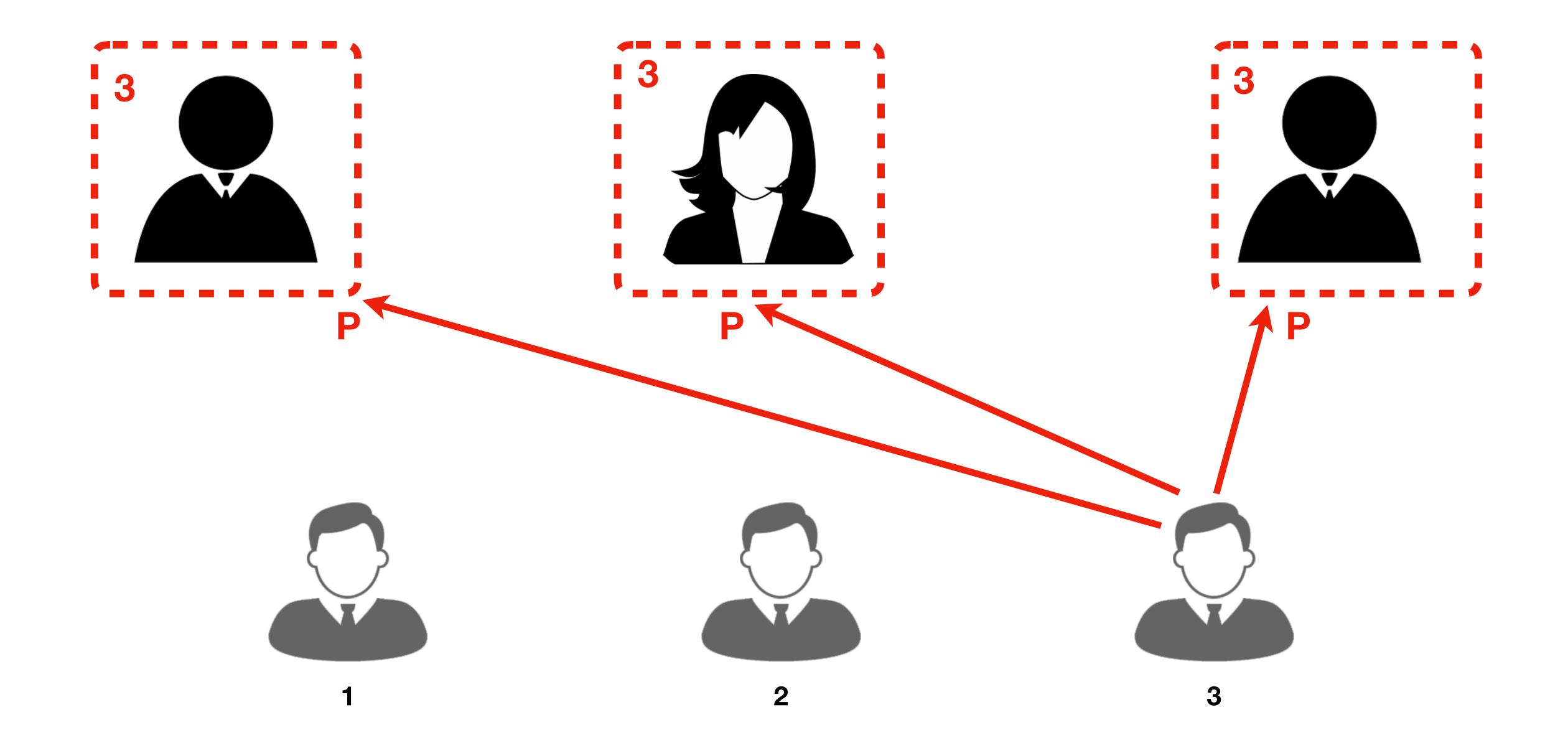






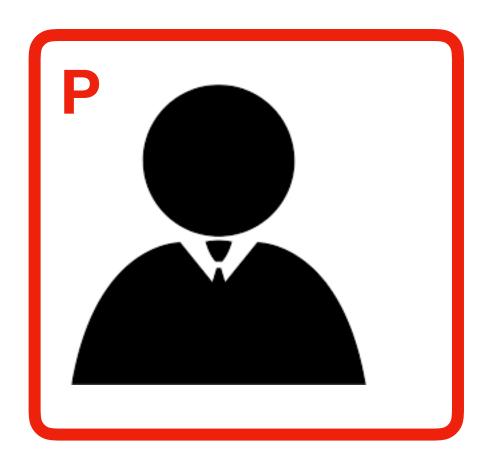


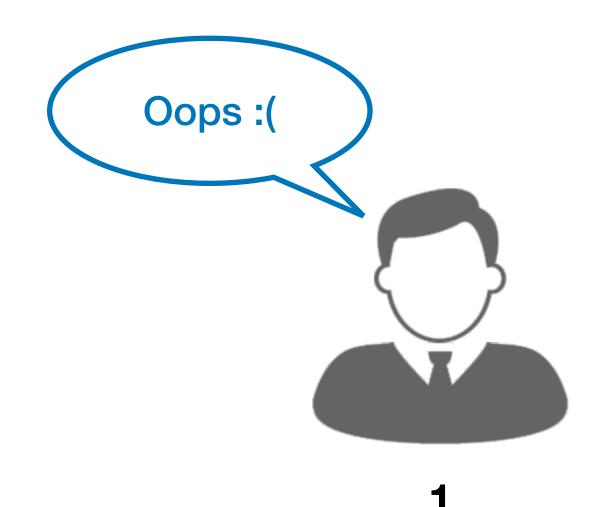














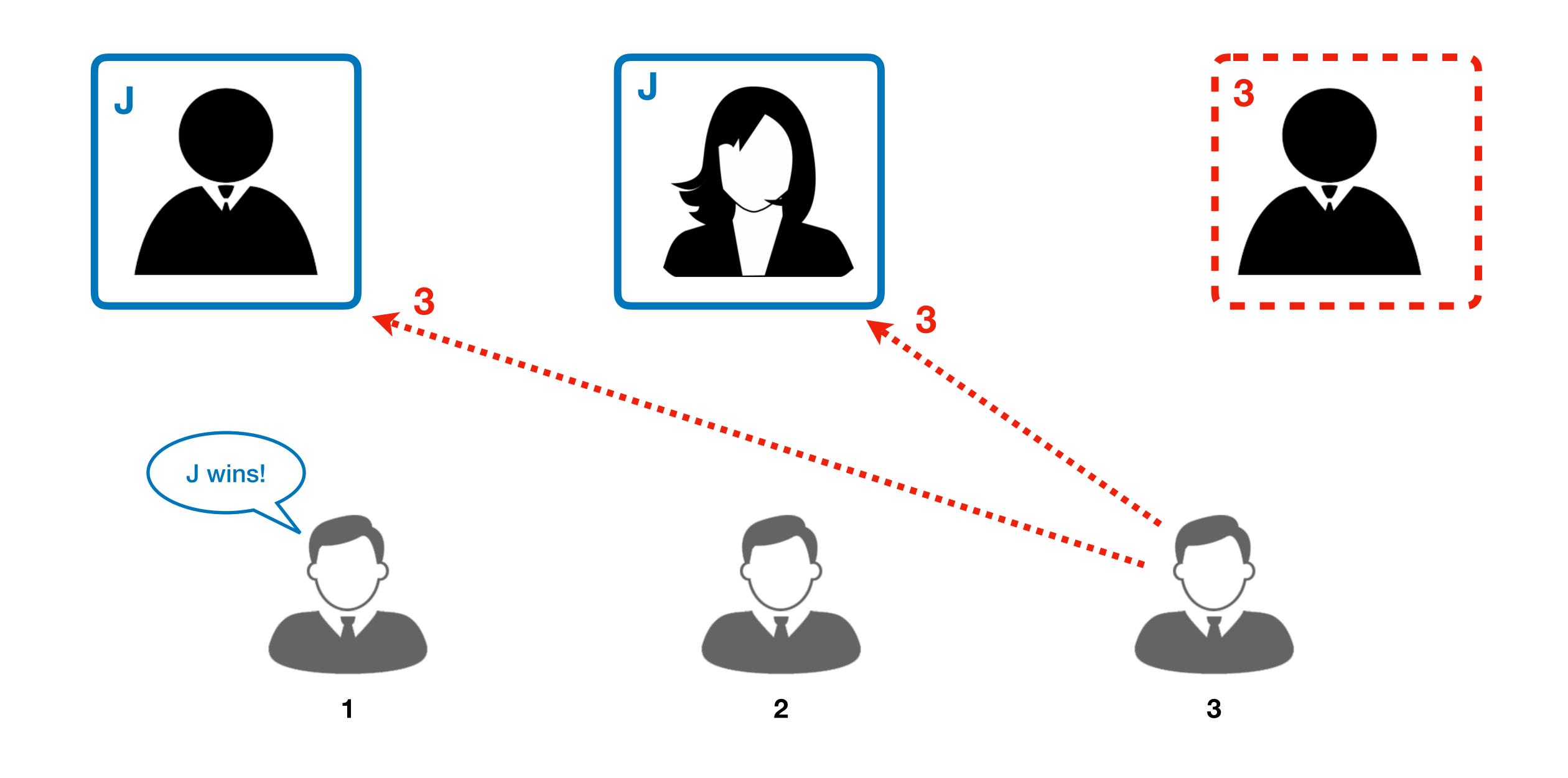


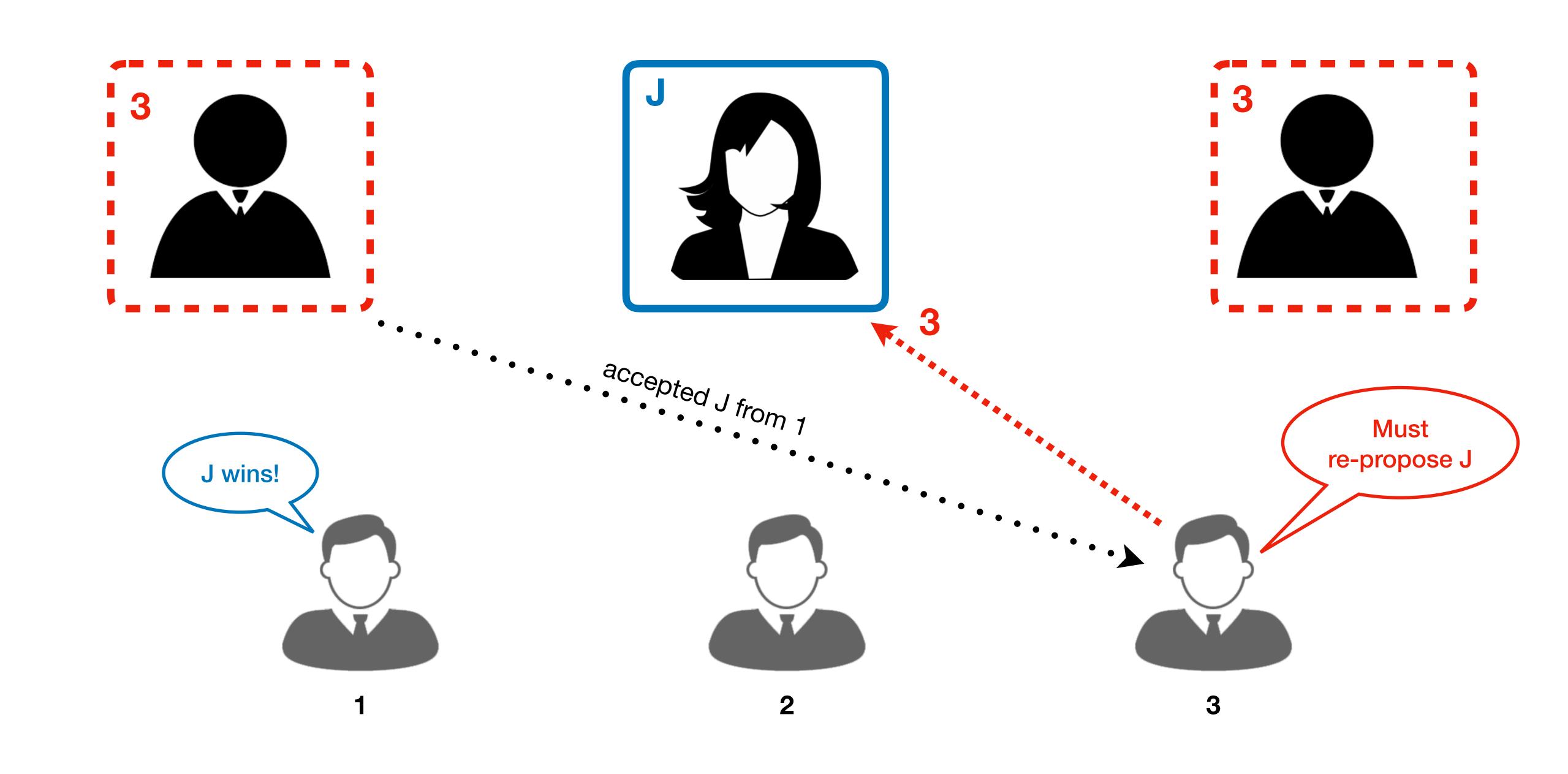
## Problem 3

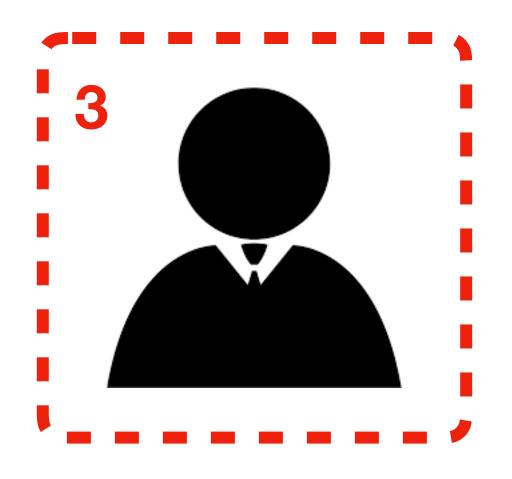
How to ensure irrevocability of consensus in the presence of *priorities* and *asynchrony*?

# Key Idea 4

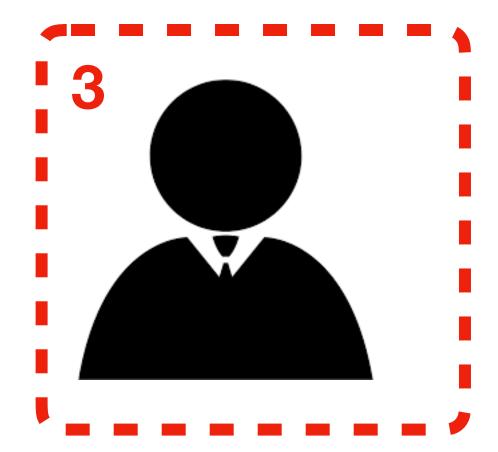
- Cooperation between Proposers and Acceptors:
  - Acceptors, when agreeing to support a proposer, must "tell" what was
    the highest-ballot value they have accepted;
  - Higher-ballot proposers re-propose already (partially) accepted values from the lower-ballot proposers, who secured the quorum before.
- This way, a proposer "knows" that, once it secured its quorum, either
  - its own proposal, or some higher-ballot one will be accepted
  - if its proposal got accepted, it will not be revoked (thanks to quorum intersection)

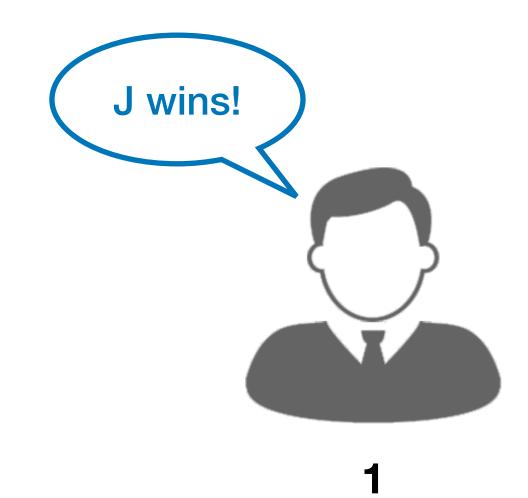




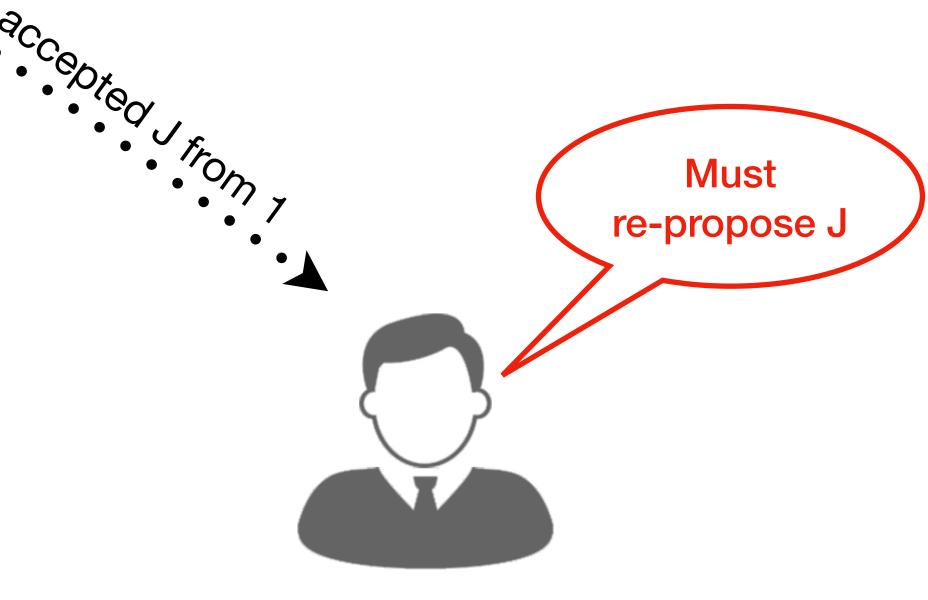


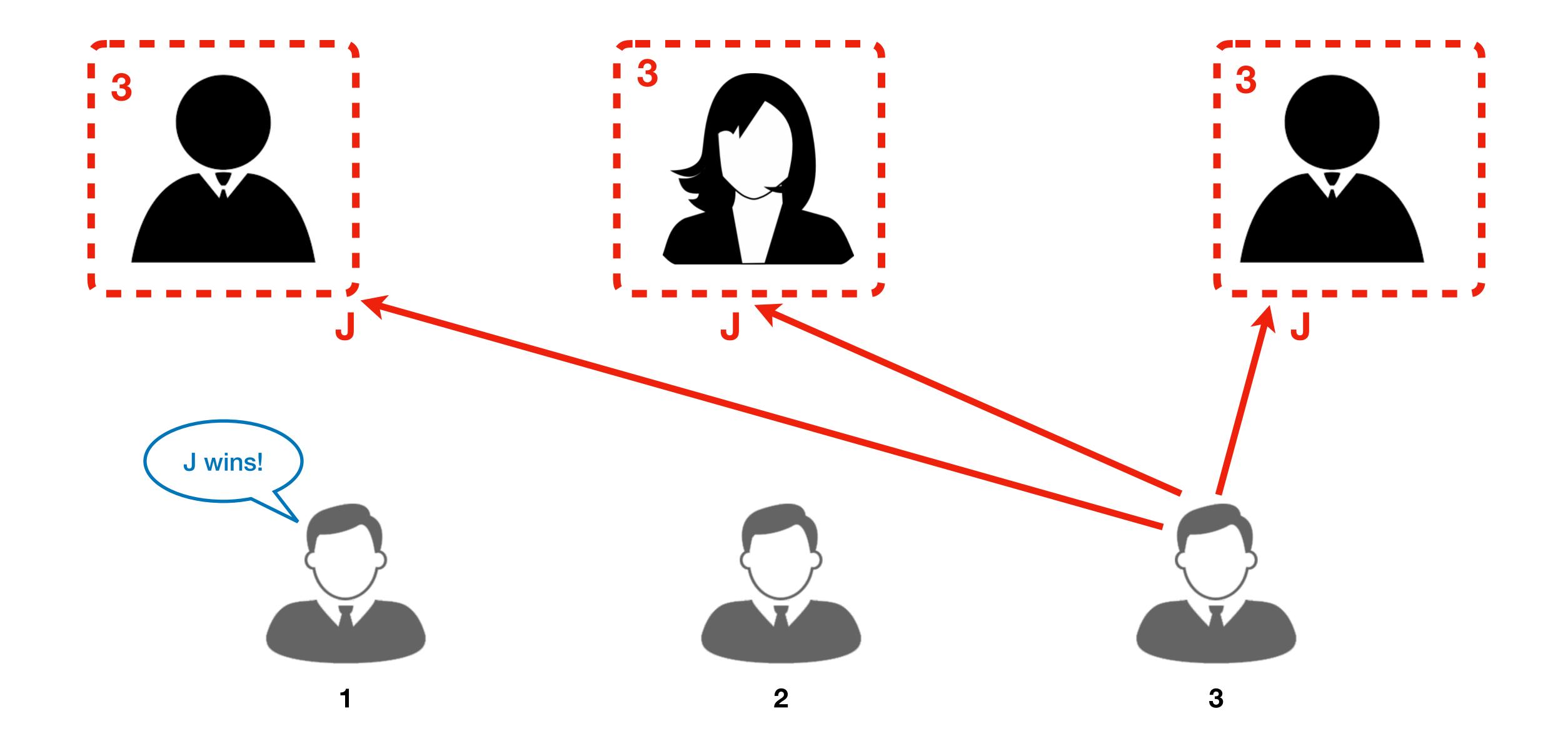


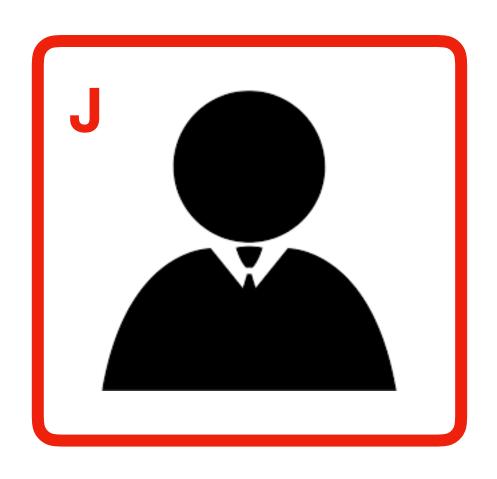


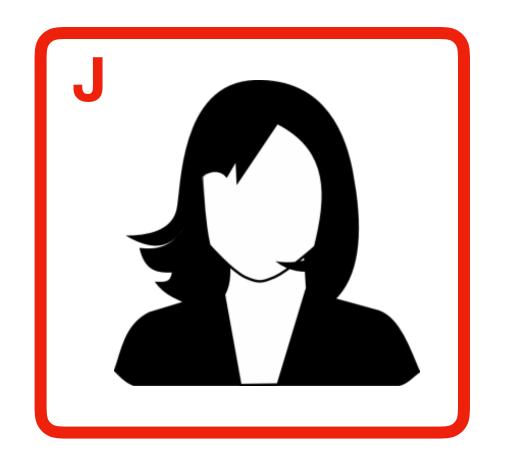


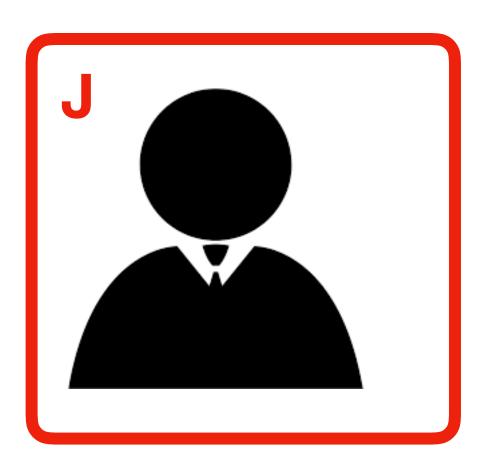


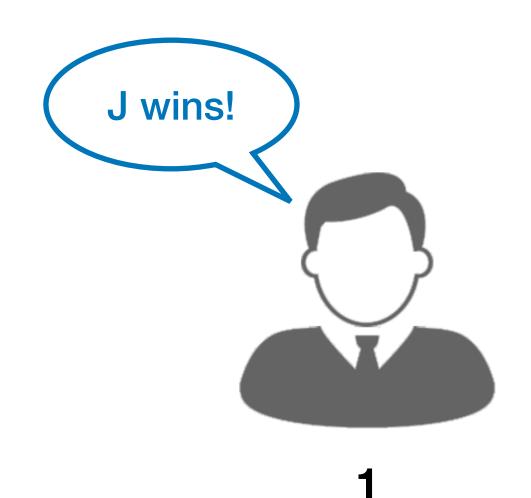




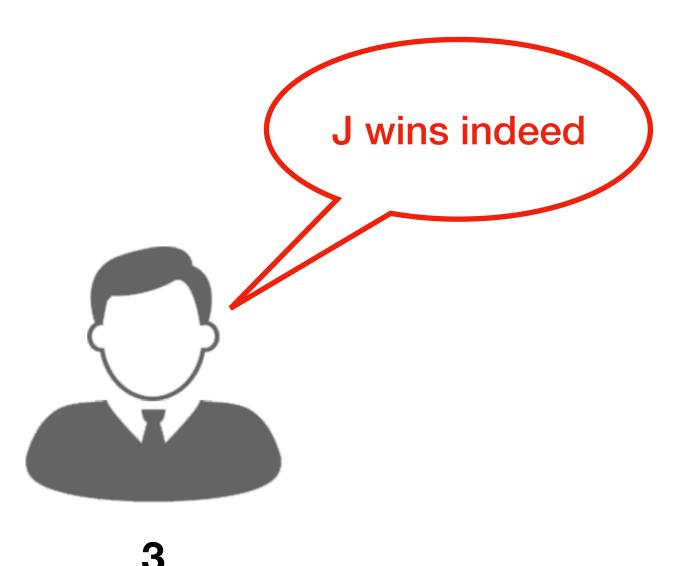












### Two-Phase Ballot-based Consensus

- Proposers suggest values, acceptors decide upon acceptance;
- Each proposal goes in two rounds:
  - Phase 1: securing a quorum of acceptors for a proposal
  - Phase 2: sending out the proposal
- Acceptors agree only to support ballots higher than what they've seen;
- They inform proposers of previously accepted values, which those then re-propose.

# The Algorithm in a Nutshell

#### Proposer

#### Acceptor

#### Phase 1

- Send my ballot **b** to all acceptors
- Wait for response of at least n/2 + 1 acceptors
- Upon receiving a ballot b
  - if it's the first one, remember it and send "ok" back.
  - if it's higher than **b'** we supported before, send back a previously accepted (b', v'), and remember **b** as what's currently supported.

#### Phase 2

- When heard back from n/2 + 1 acceptors, send them back (b, w), where
  - **b** is my ballot
  - w is the value from the acceptors with the highest ballot, or my own value.

Accept incoming value w if it comes with a ballot **b**, which we currently support; ignore otherwise.

# Learning an Accepted Value

- Send request to all acceptors;
- If at least n/2 + 1 acceptors respond back with the same value v, this is an accepted value.
- Correctness of this reasoning follows from irrevocability.

## Paxos

- A practical fault-tolerant distributed consensus algorithm;
- Invented in 1990, published in 1998;
- Nowadays used everywhere: Google (Bigtable, Chubby), IBM, Microsoft;
- You have just seen it explained.

# History of Paxos

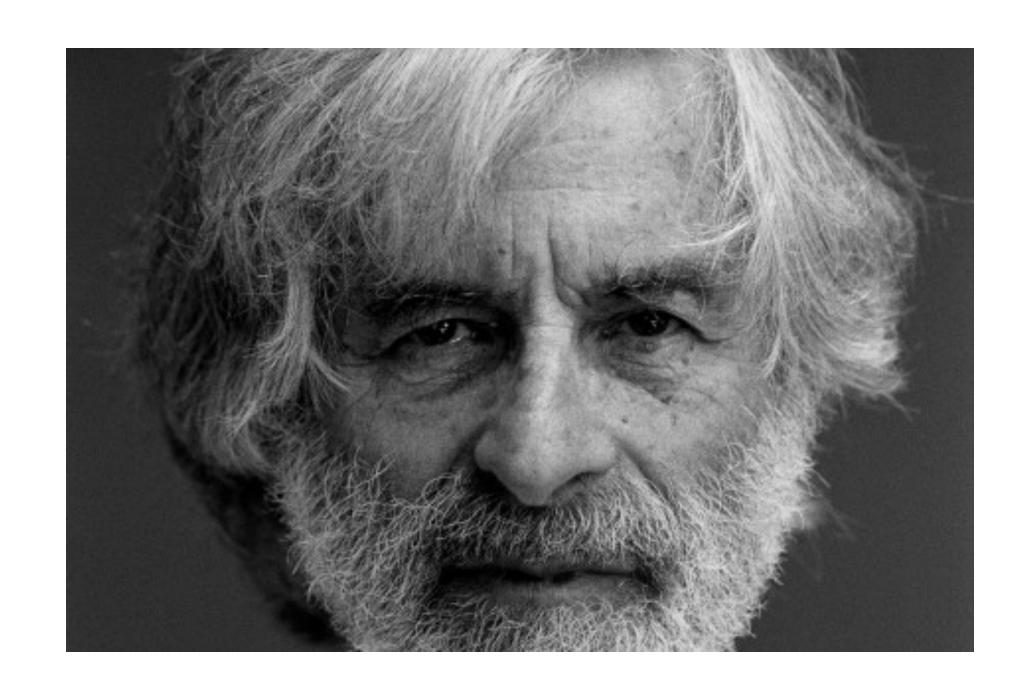
1990: Paxos first described

1998: Paxos paper published

2005: First practical deployments

2010: Widespread use!

2014: Lamport gets Turing Award



Leslie Lamport
(also known for LaTeX, Vector clocks, TLA)
Turing Award winner 2014

# History of Paxos

1990: Paxos first described

1998: Paxos paper published

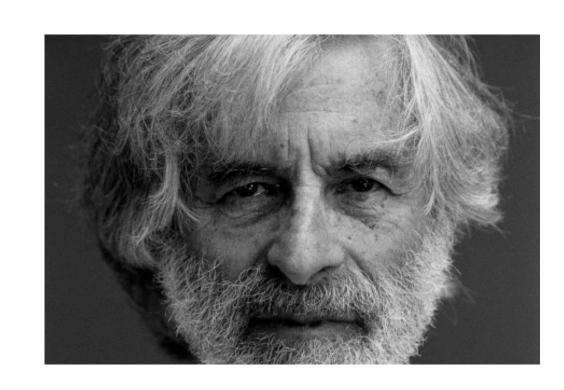
2005: First practical dep

2010: Widespread use!

2014: Lamport gets Turii

Recent archaeological discoveries on the island of Paxos reveal that the parliament functioned despite the peripatetic propensity of its part-time legislators.

The legislators maintained consistent copies of the parliamentary record, despite their frequent forays from the chamber and the forgetfulness of their messengers



Leslie Lamport
(also known for LaTeX, Vector clocks, TLA)
Turing Award winner 2014

# History of Paxos

1990: Paxos first described

1998: Paxos paper published

2014: La

• The ABCDs of Paxos [2001]

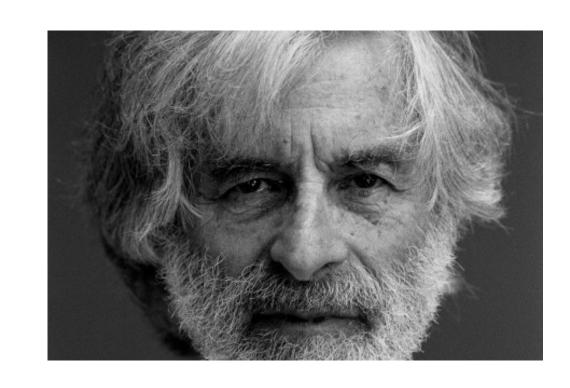
2005: Fi Paxos Made Simple [2001]

2010: W Paxos Made Practical [2007]

Paxos Made Live [2007]

• Paxos Made Moderately Complex [2011]

• Paxos Consensus, Deconstructed and Abstracted [2018]



Leslie Lamport
(also known for LaTeX, Vector clocks, TLA)
Turing Award winner 2014

## Multi-Paxos

- Presented in the original Lamport's 1998 paper.
- Uses the described idea for a sequence of "slots" (think transactions).
- Includes reconfiguration (changing set of acceptors on the fly).
- Naive implementation: run Simple Paxos for each slot.
  - Better approach secure a quorum for several slots.

# Exploring the Paxos Zoo with Network Combinators

- A framework for combining different optimisations of Simple/Multi Paxos
- Written in Scala/Akka, available at https://github.com/certichain/network-transformations
- Accompanying paper:
   Paxos Consensus, Deconstructed and Abstracted by García-Pérez et al, 2018.

```
def setupAndRunPaxos[A](slotValueMap: Map[Int, List[A]], factory: PaxosFactory[A]) {
   val acceptorNum = 7
   val learnerNum = 3
   val proposerNum = 5

   val instance = factory.createPaxosInstance(system, proposerNum, acceptorNum, learnerNum)
   proposeValuesForSlots(slotValueMap, instance, factory)

   Thread.sleep(400) // Wait for some time
   learnAcceptedValues(slotValueMap, instance, factory)
}
```

### Alternative Consensus Protocols

- View-Stamped Replication
   by Brian M. Oki and Barbara Liskov, 1989
- Raft
   by Diego Ongaro and John K. Ousterhout, 2014

## Formal Verification of Consensus

- Initially only the *model* of the protocol was verified:
  - P. Kellomäki, 2004, Simple Paxos in PVS
  - M. Jaskelioff and S. Merz, 2005, Disk Paxos in Isabelle/HOL
  - O. Padon et al. 2017, Simple/Multi-Paxos in Ivy
- Verified runnable implementations came later:
  - V. Rahli et al., 2015, Multi-Paxos in EventML
  - C. Hawblitzel et al., 2015, Multi-Paxos in **Dafny**
  - J. Wilcox et al., 2015, Raft in Coq
  - C. Dragoi et al., 2016, (Synchronous) Simple Paxos in PSync
  - A. Pillai, 2018, Simple Paxos Coq (incomplete)

## To Take Away

- Fault-Tolerant Consensus Protocols are a critical component of modern distributed systems and applications
- Consensus properties are uniformity, non-triviality, and irrevocability
- The key ideas of Lamport's Paxos protocol are:
  - Majority quorums (avoiding split brain and enabling fault-tolerance);
  - Two-phase structure (secure-commit);
  - Dichotomy and cooperation between proposers and acceptors.

# Bibliography

- L. Lamport. *The part-time parliament*. ACM Trans. Comput. Syst., 16(2):133–169, 1998.
- L. Lamport. Paxos made simple. SIGACT News, 32, 2001.
- T.D. Chandra et al. *Paxos made live: an engineering perspective*. PODC 2007
- B. W. Lampson, *The ABCD's of Paxos.* PODC 2001
- P. Kellomäki. An Annotated Specification of the Consensus Protocol of Paxos Using Superposition in PVS. 2004
- C. Dragoi et al. *PSync: a partially synchronous language for fault-tolerant distributed algorithms*. In POPL, 2016.
- M. Jaskelioff and S. Merz. Proving the correctness of disk Paxos. Archive of Formal Proofs, 2005.
- C. Hawblitzel et al. *IronFleet: proving practical distributed systems correct*. In SOSP 2015.
- D. Ongaro and J. K. Ousterhout. *In search of an understandable consensus algorithm*. USENIX Annual Technical Conference, 2014
- B.M. Oki and B. Liskov, *Viewstamped Replication: A General Primary Copy*. PODC 1988
- O. Padon, et al. *Paxos made EPR: decidable reasoning about distributed protocols.* PACMPL, 1(OOPSLA):108:1–108:31, 2017.
- V. Rahli, et al. Formal specification, verification, and implementation of fault-tolerant systems using EventML. In AVOCS. EASST, 2015.
- A. Pillai, Mechanised Verification of Paxos-like Consensus Protocols, BSc Thesis, 2018
- R. van Renesse and D. Altinbuken. Paxos Made Moderately Complex. ACM Comput. Surv., 47(3):42:1–42:36, 2015.
- J.R. Wilcox et al., Verdi: a framework for implementing and formally verifying distributed systems, PLDI 2015
- Á. García-Pérez et al., Paxos Consensus, Deconstructed and Abstracted, ESOP 2018